# Software Implementation of Numerical Algorithms in Arbitrary Precision 

Zinovi L. Krougly<br>Department of Applied Mathematics and<br>Statistical \& Actuarial Sciences<br>Western University<br>London, Ontario, Canada N6A5B7<br>Email: zkrougly@stats.uwo.ca

David J. Jeffrey<br>Department of Applied Mathematics<br>Western University<br>London, Ontario, Canada N6A5B7<br>Email: djeffrey@uwo.ca

Dina Tsarapkina<br>Department of Applied Mathematics<br>Western University<br>London, Ontario, Canada N6A5B7<br>Email: dtsarapk@uwo.ca


#### Abstract

We introduce a Matlab mprec arbitrary precision library with applications to numerical analysis. For maximum efficiency arithmetic operators and algebraic functions are implemented in the mpreal class. The examples are chosen to reflect the diversity of types of problems for which multiple precision can play a useful role.


## I. Introduction

The numerical algorithms in arbitrary precision arises in many applications of science and engineering. We have written an interface code, defined Matlab classes, and linked them to a compiled form of the ARPREC C++ source code [1].

For computational efficiency most of the basic arbitrary precision (AP) Matlab functions use the interface to C++. In addition we incorporate algorithms for ordinary differential equations, and for some advance functions such as Newton's iterations, Lambert W function, and numerical inversion of the Laplace transform that provides higher accuracy and performance. The accuracy of AP calculations can be changed by initializing certain algorithmic parameters.

## II. Implementation of the mprec Package

The mprec package includes the following basic operations and functions [2]:

- Arithmetic operations, common transcendental functions, including cos, sin, tan, arccos, arcsin, arctan, exp, $\ln , \log$, Erf, gamma and other functions
- Supports AP datatypes: mp_real,mp_int and mp_complex, vectors and matrix calculations
- Definitions of useful mathematical constants such as $e, \log _{2} e, \log _{10} e, \ln 2, \ln 10, \pi, \pi / 2, \pi / 4,1 / \pi, 2 / \pi$, $2 / \sqrt{\pi}, \sqrt{2}, 1 / \sqrt{2}$
- Matlab Code mpreal class to incorporate AP operations and functions in a natural mathematical expressions
- C++ code for AP computing, high performance and full portability
- Common numerical algorithms ( solving complex equations, Newton's iterations, ordinary differential equations, etc)
- Special routines for Matlab interface with C++: to compute fundamental mathematical constant and special values such as $\pi, e, \ln 2$, epsilon; utilize and execute string containing Matlab expressions, and convert $\mathrm{C}++$ output arguments from the expressions into strings

The mprec multiple precision function library is a collection of Matlab m-files for AP floating point calculations. In general, it is possible to write m -files for each arithmetic and algebraic operations. But this requires having to rewrite each software application which introduces significant debugging difficulties. Another important aspect to consider is the possibility of rewriting some of the fundamental applications with high performance capabilities by making only minor changes. In this regard, a more efficient approach, is to incorporate these conversions for mathematical operations as in mathematical convention, using the Matlab operator overloading features of object-oriented programming.

The mprec numbers are typically denoted by $x, y, z$, and the string variables are denoted by $s$. The software supports input, of real and complex numbers. Some of the basic operations are as follows.

To create a mprec class within the Matlab environment and provide useful functionality the following methods are implemented:

- Overloaded basic arithmetic operations: addition (+), substraction (-), multiplication (*), division (/) and power $(\wedge)$.
- Overloaded mathematical function, such as roots, $\sin , \cos , \exp , \log$ and some advanced functions and fundamental algorithms, as newton (Newton's iterations), lambertw (Lambert W function), gavste (Gaver-Stehfest algorithm for inverse Laplace transform), and rk4 (Runge-Kutta method for Ordinary differential equations).
- Overloaded relational operations: equal ( $==$ ), not equal $(!=)$, less then $(<)$, greater then $(>)$, less than or equal $(<=)$, greater than or equal $(>=)$.
See Tab. I for a basic list.
In the next sections we present some applications, where the extended precision allows for construction of efficient

TABLE I. BASIC ARBITRARY PRECISION ARITHMETIC AND ALGEBRAIC OPERATIONS IMPLEMENTED IN mpreal CLASS

| No | Function | Operation | Data Type |
| :---: | :---: | :---: | :---: |
| 1. | $\mathrm{z}=\mathrm{x}+\mathrm{y}$ | $\mathrm{z}=\mathrm{x}+\mathrm{y}$ | $x, y, z$ AP complex |
| 2. | $\mathrm{z}=\mathrm{x}-\mathrm{y}$ | $\mathrm{z}=\mathrm{x}-\mathrm{y}$ | $x, y, z$ AP complex |
| 3. | $\mathrm{z}=\mathrm{x} \times \mathrm{y}$ | $\mathrm{z}=\mathrm{x} \times \mathrm{y}$ | $x, y, z$ AP complex |
| 4. | $z=x / y$ | $z=x / y$ | $x, y, z$ AP complex |
| 5. | $\mathrm{z}=\sin (\mathrm{x})$ | $\mathrm{z}=\sin (\mathrm{x})$ | $\mathrm{x}, \mathrm{z}$ AP real |
| 6. | $\mathrm{z}=\cos (\mathrm{x})$ | $\mathrm{z}=\cos (\mathrm{x})$ | $\mathrm{x}, \mathrm{z}$ AP real |
| 7. | $\mathrm{z}=\operatorname{asin}(\mathrm{x})$ | $\mathrm{z}=\arcsin (\mathrm{x})$ | $x, \mathrm{z} \mathrm{AP} \mathrm{real}$ |
| 8. | $\mathrm{z}=\operatorname{acos}(\mathrm{x})$ | $\mathrm{z}=\arccos (\mathrm{x})$ | $x, \mathrm{z}$ AP real |
| 9. | $\mathrm{z}=\operatorname{atan}(\mathrm{x})$ | $\mathrm{z}=\arctan (\mathrm{x})$ | $\mathrm{x}, \mathrm{z}$ AP real |
| 10 | $\mathrm{z}=\exp (\mathrm{x})$ | $z=e^{x}$ | x, z AP complex |
| 11. | $\mathrm{z}=\log (\mathrm{x})$ | $\mathrm{z}=\ln (\mathrm{x})$ | $\mathrm{x}, \mathrm{z} \mathrm{AP} \mathrm{real}$ |
| 12 | $\mathrm{z}=\operatorname{sqrt}(\mathrm{x})$ | $\mathrm{z}=\sqrt{x}$ | $\mathrm{x}, \mathrm{z}$ AP real |
| 13. | $\mathrm{z}=x^{\wedge} \mathrm{n}$ | $\mathrm{z}=x^{n}$ | $\mathrm{x}, \mathrm{z}$ AP real, n integer |
| 14. | $\mathrm{z}=x^{\wedge} \mathrm{y}$ | $\mathrm{z}=x^{y}$ | $x, y, z$ AP real |
| 15. | $\mathrm{z}=$ double $(\mathrm{x})$ | Conversion | x string, z double |
| 16. | $\mathrm{z}=\operatorname{char}(\mathrm{x})$ | Conversion | x AP, string, z AP complex |
| 17. | $\mathrm{z}=\operatorname{char}(\mathrm{x})$ | Conversion | x AP, string, z AP complex |

TABLE II. TABLE OF LAPLACE AND INVERSE TRANSFORMS FOR TEST FUNCTIONS USED IN NUMERICAL CALCULATIONS

| $F_{01}(s)=s^{-1 / 2} e^{-s}-1$ | $f_{01}(t)=(\pi t)^{-1 / 2} \cos \left(2 t^{1 / 2}\right)$ |
| :--- | :--- |
| $F_{02}(s)=(s+1 / 2)^{-1}$ | $f_{02}(t)=e^{-t / 2}$ |
| $F_{03}(s)=\left((s+0.2)^{2}+1\right)^{-1}$ | $f_{03}(t)=e^{-0.2 t} \sin (t)$ |
| $F_{04}(s)=s^{-2}$ | $f_{04}(t)=t$ |
| $F_{05}(s)=\left(s^{2}+1\right)^{-1}$ | $f_{05}(t)=\sin (t)$ |
| $F_{06}(s)=\left(s^{2}-1\right)\left(s^{2}+1\right)^{-2}$ | $f_{06}(t)=t \cos (t)$ |
| $F_{07}(s)=(s+1 / 2)^{1 / 2-}$ | $f_{07}(t)=\left(e^{-t / 4}-e^{-t / 2}\right) \times$ |
|  | $(s+1 / 4)^{1 / 2}$ |
| $F_{08}(s)=e^{-4 s^{1 / 2}}$ | $f_{08}(t)=2 e^{-4 / t}\left(\pi t^{3}\right)^{-1 / 2}$ |
| $F_{09}(s)=\tan \left(s^{-1}\right)$ | $f_{09}(t)=t^{-1} \sin (t)$ |
| $F_{10}(s)=\frac{e^{-1 / s}}{\sqrt{s}}$ | $f_{10}(t)=\frac{\cos (2 \sqrt{t})}{\sqrt{\pi * t)}}$ |

algorithms.

## III. Gaver-Stehfest algorithm for inverse LAPLACE TRANSFORM

The numerical inversion of Laplace transform arises in many areas of science and engineering. Stehfest [3] derived the Gaver-Stehfest algorithm for the numerical inversion of Laplace transforms. For most of the more interesting problems, however, numerical inverting often has numerical accuracy problems [4], [5], [6]). As such, small rounding errors in computation may significantly offset the results, rendering these algorithms impractical to apply. With extended precision, we are able to add additional significant figures, and in doing so produce results that converge to the solution without falling victim to the serve truncation that may happen in standard double arithmetic.

This demonstration applies the algorithm to determine the inverse Laplace transforms of ten test functions to various type numerical accuracy. The inverse functions and corresponding test functions are presented in Tab. II. The first nine function are taken from [4], and the last one from [5].

The Gaver-Stehfest method uses the summation:

$$
\begin{equation*}
f(t) \approx \ln 2 / t \sum_{n=1}^{N} K_{n} F(n \ln 2 / t) \tag{1}
\end{equation*}
$$

The $K_{n}$ coefficients only depend on the number of expansion terms, $N$ (which must be even), they are:

TABLE III. CALCULATION ERRORS OF THE INVERSE LAPLACE TRANSFORM IN DOUBLE PRECISION FOR THE FUNCTIONS IN TAB. II. Values $1.7 \mathrm{E}-4 \equiv 1.7 \times 10^{-4}$

|  | $\mathrm{N}=8$ | $\mathrm{~N}=16$ | $\mathrm{~N}=18$ | $\mathrm{~N}=32$ |
| :---: | :---: | :---: | :---: | :---: |
| $F_{01}$ | $1.2 \mathrm{E}+0$ | $1.7 \mathrm{E}-4$ | $3.6 \mathrm{E}-4$ | $8.0 \mathrm{E}+5$ |
| $F_{02}$ | $1.7 \mathrm{E}-1$ | $2.0 \mathrm{E}-4$ | $1.6 \mathrm{E}-4$ | $2.6 \mathrm{E}+5$ |
| $F_{03}$ | $1.7 \mathrm{E}+1$ | $2.2 \mathrm{E}+0$ | $1.1 \mathrm{E}+0$ | $5.1 \mathrm{E}+4$ |
| $F_{04}$ | $9.3 \mathrm{E}-2$ | $2.6 \mathrm{E}-5$ | $8.4 \mathrm{E}-5$ | $7.1 \mathrm{E}+4$ |
| $F_{05}$ | $5.1 \mathrm{E}+1$ | $1.1 \mathrm{E}+1$ | $5.9 \mathrm{E}+0$ | $6.2 \mathrm{E}+4$ |
| $F_{06}$ | $2.6 \mathrm{E}+2$ | $8.1 \mathrm{E}+1$ | $6.4 \mathrm{E}+1$ | $5.4 \mathrm{E}+4$ |
| $F_{07}$ | $4.4 \mathrm{E}-3$ | $5.7 \mathrm{E}-4$ | $1.1 \mathrm{E}-2$ | $2.1 \mathrm{E}+7$ |
| $F_{08}$ | $9.7 \mathrm{E}-2$ | $1.8 \mathrm{E}-3$ | $6.6 \mathrm{E}-4$ | $1.1 \mathrm{E}+3$ |
| $F_{09}$ | $8.9 \mathrm{E}+0$ | $1.2 \mathrm{E}+0$ | $6.2 \mathrm{E}-1$ | $2.9 \mathrm{E}+5$ |
| $F_{10}$ | $1.9 \mathrm{E}+0$ | $1.7 \mathrm{E}-4$ | $3.8 \mathrm{E}-4$ | $7.6 \mathrm{E}+5$ |

$$
\begin{equation*}
K_{n}=\sum_{k=[(n+1) / 2]}^{\min (n, N / 2)} \frac{(-1)^{n+N / 2} k^{N / 2}(2 k)!}{\left(\frac{N}{2}-k\right)!k!(k-1)!(n-k)!(2 k-n)!} . \tag{2}
\end{equation*}
$$

For each function we calculate an error, $E$, defined by

$$
\begin{equation*}
E=\left(\sum_{i=1}^{30}\left(f(i / 2)-f_{\alpha}(i / 2)\right)^{2} / 30\right)^{1 / 2} \tag{3}
\end{equation*}
$$

as the measure for the accuracy of the numerical solution [4]. Let $f(t)$ be the analytical solution. We denote by $f \alpha(t)$ the numerical estimate of the exact solution. Then $E$ gives the root-mean-square deviation between the analytical and numerical solutions for the $t$ values $0.5,1,1.5, \ldots, 15$.

The $K_{n}$ coefficients become very lalrge and alternate in sign for increasing $n$. The sum (1) begins to suffer from cancelation for large $N \geq$ the number of decimal digits of precision (e.g., double precision $=16$ ).

1) Testing Gaver-Stehfest inversion algorithms in double precision: In Tab. III we report some numerical results related to the test functions presented in Tab. II.

All the calculations in Tab. III were done in double precision. In Tab. II we show a number of functions and their exact inverse functions. The numerical solutions for the functions in Tab. II were compared to 200 points along the exact solution, and their norms were added. Table III shows the sums of these errors which gives a numerical representation of how good a solution truly is.

When looking at numerical inversion, it is important to note the accuracy with a varying number of terms and precision. We compare the inverses using Matlab Gaver-Stehfest implementation and observe the accuracy of the inversions as we increase the number of the expansion terms and precision. However, there exists a limit to adding additional terms. As we increase the number of terms, N , in the computation we quickly discover that the numerical inversion becomes unstable and our function is dominated by numerical error. For double precision it is reasonable to only allow a number $N=18$. In many cases 18 expansion terms is sufficient to approximate a function almost exactly, however there are times where a noticeable difference is seen. We have provided a number of trial functions whose exact solutions are known, to identify the ones that would benefit from the use of extended precision. Using extended precision allows to combat the
numerical limitation that we experience when dealing with double precision. Thus, we can use a larger number of terms for those functions without encountering noise.

The calculations in double precision for all functions and any number of terms are at most roughly $10^{-5}$. The accuracy is very poor (the functions $F_{03}, F_{05}, F_{06}$ and $F_{09}$ ). The convergence is poor for all these functions for the number of terms $N=8,16,18$, and even worse if the number of terms $N \geq 32$. If we continue increase the number of terms, i.e. for $N=128$, we get NaN indicating Not-a-Number, that the Gaver-Stehfest algorithm in double precision was unable to provide even an order of magnitude estimates.

The results shown in Fig. 1 - Fig. 10 correspond to the function $F_{01}-F_{10}$ in Tab. II. The inverse Laplace transforms are given for ten functions evaluated in double precision. The curves illustrate the solutions for different number of expansion terms in comparison to the exact solution. The term "exact solution" in the figures means the numerical estimate of the exact solution.

In figures Fig. 2, Fig. 4 and Fig. 7 even with only $N=8$ expansion terms we are able to converge to the solutions which are indistinguishable to the eye.

The Fig. 1, Fig. 8 and Fig. 10 provide the solutions that are indistinguishable to the eye between $N=16$ and $N=18$. The value $N$ is chosen to provide the closest solution to the exact value. Due to the functions being slightly different, the error may begin to worsen the solution at an earlier term ( $\mathrm{N}=18$ ), or the additional terms may continue to benefit the solution even with 16 digits.

In the remaining figures, Fig. 3, Fig. 5 Fig. 6 and Fig. 9, we can see the difference between the best approximation and the exact solution. For these problems, arbitrary precision is of interest. We are able to add additional terms to improve the solution, and delay the onset of the noise.

In all the figures, when looking at the plot using $N=32$ we see that using too many terms causes rounding error to overtake the numerical solution, and we essentially obtain noise. This is because as small changes in large numbers are manipulated, we experience severe truncation of the changes which lead to unstable solutions.
2) Implementation of Gaver-Stehfest algorithm in arbitrary precision: The Gaver-Stehfest algorithm was implemented in arbitrary precision, taking advantage of the arbitrary number of significant digits. Below is a demonstration of how the package can be used to compute an inverse Laplace transform on a function predefined in our code. The parameter fun represents the name of the function to be transformed, i.e. fun $=1$ corresponds to the function $F_{01}$ in Tab.II. The time at which the inverse Laplace transform of the original function is required is denoted by $t . N$ is the number of expansion terms to be used in the computation, which must be an even number, and prec is the precision to be used. The path_reflects the path to the C++ mpcalc dll project, where Gaver-Stehfest algorithm (function gavste) employed. Upon running this test function script, we will obtain in the output the value of the inverse Laplace transform, invlt and the err corresponds to formula (3) when this result is compared to the numerical estimate of the exact value.


Fig. 1. Inverse Laplace transform of the function $F_{01}$ evaluated in double precision


Fig. 2. Inverse Laplace transform of the function $F_{02}$ evaluated in double precision


Fig. 3. Inverse Laplace transform of the function $F_{03}$ evaluated in double precision

The test function can be run with the code below

```
* Numerical inversion of the Laplace transform using Gaver-Stehfest
% algorithm with extended precision calculations
function [inv_lt, err] = gavste_test(fun,t,L, prec)
function
    fun The name of the function to be inverse transformed
        (the number corresponds to test function in mpcalc
        dll project)
    The value of t where the inverse Laplace transform
    to the (unknown)
    original function }f(t)\mathrm{ is required ( }t>0\mathrm{ ), usually
    a snapshot of time(examples: t = 0.5, 1, 1.5, ...
    15, so on)
```



```
    (examples: N =4,16, 32, 64, 128, 256, so on)
    calculations digits in arbitrary precision
        calculations used (examples: prec = 16, 32, 100,
        ..., 1000)
    invlt The value of the inverse laplace transform
    Error of the inverse Laplace transform
    Example: [inv_lt, err] = test gavste(1,2,32,100)
global path_ precision;
global p
precision = prec;
precision = prec;
k = fun;
kp = mpreal ([k,L
tn = mpreal (t)
tn.imag = 100;
responce = gavste(kp,tn, fn);
nv_lt = responce.real;
*)
responce = gavste(kp,tn,fn)
err = responce.real;
```

The output is:



Fig. 4. Inverse Laplace transform of the function $F_{04}$ evaluated in double precision

TABLE IV. CALCULATION ERRORS OF THE INVERSE LAPLACE TRANSFORM IN ARBITRARY PRECISION (100 DIGITS) FOR THE FUNCTIONS IN TAB. II. Values $9.6 \mathrm{E}-2 \equiv 9.6 \times 10^{-2}$

|  | $\mathrm{N}=4$ | $\mathrm{~N}=16$ | $\mathrm{~N}=32$ | $\mathrm{~N}=64$ | $\mathrm{~N}=128$ | $\mathrm{~N}=256$ |
| :---: | ---: | ---: | ---: | ---: | ---: | ---: |
| $F_{01}$ | $9.60 \mathrm{E}-2$ | $1.6 \mathrm{E}-4$ | $8.1 \mathrm{E}-12$ | $1.8 \mathrm{E}-26$ | $2.3 \mathrm{E}-33$ | $6.3 \mathrm{E}+53$ |
| $F_{02}$ | $1.5 \mathrm{E}-2$ | $6.4 \mathrm{E}-6$ | $5.2 \mathrm{E}-11$ | $1.3 \mathrm{E}-23$ | $3.4 \mathrm{E}-34$ | $6.1 \mathrm{E}+52$ |
| $F_{03}$ | $1.7 \mathrm{E}-1$ | $5.0 \mathrm{E}-2$ | $4.4 \mathrm{E}-3$ | $4.4 \mathrm{E}-7$ | $1.5 \mathrm{E}-21$ | $1.0 \mathrm{E}+52$ |
| $F_{04}$ | $3.4 \mathrm{E}-1$ | $3.9 \mathrm{E}-7$ | $1.5 \mathrm{E}-14$ | $3.1 \mathrm{E}-29$ | $1.4 \mathrm{E}-34$ | $1.1 \mathrm{E}+52$ |
| $F_{05}$ | $6.6 \mathrm{E}-1$ | $4.7 \mathrm{E}-1$ | $1.4 \mathrm{E}-1$ | $1.3 \mathrm{E}-4$ | $1.0 \mathrm{E}-17$ | $1.1 \mathrm{E}+52$ |
| $F_{06}$ | $6.0 \mathrm{E}+0$ | $5.2 \mathrm{E}+0$ | $1.9 \mathrm{E}+0$ | $7.0 \mathrm{E}-3$ | $5.6 \mathrm{E}-16$ | $1.1 \mathrm{E}+56$ |
| $F_{07}$ | $6.3 \mathrm{E}-4$ | $6.4 \mathrm{E}-8$ | $1.9 \mathrm{E}-13$ | $2.7 \mathrm{E}-26$ | $1.3 \mathrm{E}-31$ | $7.2 \mathrm{E}+55$ |
| $F_{08}$ | $3.6 \mathrm{E}-3$ | $6.8 \mathrm{E}-6$ | $2.3 \mathrm{E}-9$ | $1.9 \mathrm{E}-16$ | $8.6 \mathrm{E}-31$ | $2.5 \mathrm{E}+52$ |
| $F_{09}$ | $1.1 \mathrm{E}-1$ | $4.1 \mathrm{E}-2$ | $7.5 \mathrm{E}-3$ | $4.9 \mathrm{E}-6$ | $8.6 \mathrm{E}-20$ | $4.6 \mathrm{E}+59$ |
| $F_{10}$ | $9.6 \mathrm{E}-2$ | $1.6 \mathrm{E}-4$ | $8.1 \mathrm{E}-12$ | $2.0 \mathrm{E}-26$ | $2.3 \mathrm{E}-33$ | $6.3+\mathrm{E} 53$ |

invlt $=10$ ~ $-1 \times-3.795389758243676381129800678241861148 \ldots$
840967617592231946344278938954985244981787821768215557460943428
err $=10 \sim-12 \times 8.137622462175380948241428517793674051945 .$.
118475730848296549470231938397691733197561032902744637450831

Next we report some numerical results in AP to the test functions presented in Tab. II. The calculations are given in Tab. IV for 100 digits and Tab. V for 1000 digits.

For the number of terms preceding 100, the accuracy is poor (particularly in the functions $F_{05}$ and $F_{06}$ ) and improves


Fig. 5. Inverse Laplace transform of the function $F_{05}$ evaluated in double precision

TABLE V. Calculation errors of the inverse Laplace TRANSFORM IN ARBITRARY PRECISION ( 1000 DIGITS) FOR THE Functions in Tab. II. Values 9.6E-2 $\equiv 9.6 \times 10^{-2}$

|  | $\mathrm{N}=16$ | $\mathrm{~N}=32$ | $\mathrm{~N}=64$ | $\mathrm{~N}=128$ | $\mathrm{~N}=256$ |  |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
|  | $\mathrm{~N}=512$ |  |  |  |  |  |
| $F_{01}$ | $1.6 \mathrm{E}-4$ | $8.1 \mathrm{E}-12$ | $2.0 \mathrm{E}-26$ | $1.3 \mathrm{E}-55$ | $7.6 \mathrm{E}-114$ | $4.0 \mathrm{E}-230$ |
| $F_{02}$ | $6.4 \mathrm{E}-6$ | $5.2 \mathrm{E}-11$ | $1.3 \mathrm{E}-23$ | $5.0 \mathrm{E}-55$ | $5.1 \mathrm{E}-119$ | $2.8 \mathrm{E}-235$ |
| $F_{03}$ | $5.0 \mathrm{E}-2$ | $4.4 \mathrm{E}-3$ | $4.4 \mathrm{E}-7$ | $1.5 \mathrm{E}-21$ | $6.8 \mathrm{E}-66$ | $6.2 \mathrm{E}-178$ |
| $F_{04}$ | $3.9 \mathrm{E}-7$ | $1.5 \mathrm{E}-14$ | $3.1 \mathrm{E}-29$ | $2.0 \mathrm{E}-58$ | $1.2 \mathrm{E}-116$ | $6.4 \mathrm{E}-233$ |
| $F_{05}$ | $4.7 \mathrm{E}-1$ | $1.4 \mathrm{E}-1$ | $1.3 \mathrm{E}-4$ | $1.0 \mathrm{E}-17$ | $2.0 \mathrm{E}-60$ | $1.9 \mathrm{E}-175$ |
| $F_{06}$ | $5.2 \mathrm{E}+0$ | $1.9 \mathrm{E}+0$ | $7.0 \mathrm{E}-3$ | $5.6 \mathrm{E}-16$ | $3.0 \mathrm{E}-58$ | $2.6 \mathrm{E}-173$ |
| $F_{07}$ | $6.4 \mathrm{E}-8$ | $1.9 \mathrm{E}-13$ | $2.7 \mathrm{E}-26$ | $1.3 \mathrm{E}-58$ | $7.6 \mathrm{E}-120$ | $4.3 \mathrm{E}-236$ |
| $F_{08}$ | $6.8 \mathrm{E}-6$ | $2.3 \mathrm{E}-9$ | $1.9 \mathrm{E}-16$ | $8.7 \mathrm{E}-31$ | $1.9 \mathrm{E}-59$ | $1.4 \mathrm{E}-120$ |
| $F_{09}$ | $4.1 \mathrm{E}-2$ | $7.5 \mathrm{E}-3$ | $4.9 \mathrm{E}-6$ | $8.6 \mathrm{E}-20$ | $1.9 \mathrm{E}-62$ | $9.6 \mathrm{E}-179$ |
| $F_{10}$ | $1.6 \mathrm{E}-4$ | $8.1 \mathrm{E}-12$ | $2.0 \mathrm{E}-26$ | $1.3 \mathrm{E}-55$ | $7.6 \mathrm{E}-114$ | $4.0 \mathrm{E}-230$ |

to at most roughly $10^{-17}$ if we increase the number of terms to 128 . Further increase the number of terms to 256 doesn't provide convergence due to roundoff errors.

For the number of presiding 1000, the accuracy is very good for all functions and is at least roughly $10^{-16}, 10^{-58}$ and $10^{-120}$ for the number of terms accordingly $\mathrm{N}=128$, 256, and 512.

The MATLAB functions can be evaluated using either command syntax or function syntax. The code inside Matlab


Fig. 6. Inverse Laplace transform of the function $F_{06}$ evaluated in double precision
functions above will be executed when you call the function. The functions are flexible, you can call them using different arguments. See comments inside the functions for explanation.

Many test examples illustrate different aspects of arbitrary precision numerical techniques.

## IV. Conclusion

We have introduced the arbitrary precision library, as a collection of Matlab m-files. With the assistance of the implemented mpreal class, we presented the arithmetic and algebraic operations as in mathematical convention. For maximum efficiency, many of the functions are implemented by interfacing Matlab to C++.

The list of classical algorithms are implemented, such as Newton's iterations, Lambert W function, and Runge-Kutta algorithm for ordinary differential equations.

We discussed in detail the implementation of the GaverStehfest algorithm for the Laplace transform inversion allowing the advantage of using an arbitrary number of significant digits. We observe the accuracy of the inversions as we increase the number of the expansion terms and precision, which ultimately leads to stable solutions.


Fig. 7. Inverse Laplace transform of the function $F_{07}$ evaluated in double precision

## REFERENCES

[1] D. H. Bailey, Y. Hida, X. L. Li, B. Thompson, ARPREC: An Arbitrary Precision Computation Package, http://crd.lbl.gov/ dhbailey/dhbpapers/arprec.pdf., 2002.
[2] Z. L. Krougly, D. J. Jeffrey, Implementation and Application of Extended Precision in Matlab, in: N. Mastorakis et al (Eds.), Proceedings of the Applied Computing Conference ACC'09, WSEAS Press, 2009: 103-108.
[3] H. Stehfest, Algorithm 368: Numerical Inversion of Laplace Transform, Communications of the ACM, 13(1), 1970: 4749.
[4] B. Davies, B. Martin, Numerical Inversion of the Laplace Transform, A Survey and Comparison of Methods, Journal of Computational Physics 33(1), 1979: 132.
[5] A. Murli, M. Rizzardi, Algorithm 682 Talbots Method for the Laplace Inversion Problem, ACM Transactions on Mathematical Software 16(2), 1990: 158-168.
[6] K. L. Kuhlman, Review of Inverse Laplace Transform Algorithms for Laplace-Space Numerical Approaches, Numerical algorithms 63(2), 2013: 339-355.


Fig. 8. Inverse Laplace transform of the function $F_{08}$ evaluated in double precision


Fig. 9. Inverse Laplace transform of the function $F_{09}$ evaluated in double precision


Fig. 10. Inverse Laplace transform of the function $F_{10}$ evaluated in double precision

