

Package ‘FitAR’

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Title AR and Subset AR Modelling

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Description Complete functions are given for model identification, estimation and diagnostic checking for AR and subset AR models. Two types of subset AR models are supported. One family of subset AR models, denoted by ARp, is formed by taking subet of the original AR coefficients and in the other, denoted by ARz, subsets of the partial autocorrelations are used. The main advantage of the ARp model is its applicability to very large order models. For the nonsubset, AR(p), case, the function given in this package outperforms the built-in R function "ar" for exact mle when p is large. In addition to speed, another advantage of this package is that it is entirely written in the R language which makes it easier to port to other systems such as Mathematica or MatLab.

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URL <http://www.stats.uwo.ca/faculty/aim>

R topics documented:

AR1Est	3
ARSdf	4
ARToMA	4
ARToPacf	5
AcfPlot	6
BackcastResidualsAR	7
Boot.FitAR	8
Boot	9
Boot.ts	10
BoxCox.Arima	11
BoxCox.FitAR	13
BoxCox	14
BoxCox.numeric	15
BoxCox.ts	16

ChampernowneD	17
DetAR	19
FastLoglikelihoodAR	20
FitAR	21
FitARLS	23
FromSymmetricStorageUpper	25
Get1G	25
GetARMeanMLE	26
GetB	27
GetFitAR	28
GetFitARLS	29
GetKappa	30
GetLeapsAR	30
InformationMatrixAR	32
InformationMatrixARp	33
InformationMatrixARz	34
InvertibleQ	35
Jacobian	36
JacobianK	37
JarqueBeraTest	37
LBQPlot	38
LjungBoxTest	39
LoglikelihoodAR	41
Ninemile	42
PacfDL	43
PacfPlot	44
PacfToAR	45
PlotARSdf	46
RacfPlot	47
Readts	48
SelectModel	49
SeriesA	51
SiddiquiMatrix	52
SimulateGaussianAR	53
TacfAR	54
TacfMA	55
TimeSeriesPlot	56
USTobacco	57
VarianceRacfAR	58
VarianceRacfARp	59
VarianceRacfARz	60
Willamette	61
bxcx	62
coef.FitAR	63
fitted.FitAR	64
plot.FitAR	64
plot.Selectmodel	65
print.FitAR	66
residuals.FitAR	67
sdfplot.Arima	67
sdfplot.FitAR	68
sdfplot	69

sdfplot.ar	70
sdfplot.numeric	71
sdfplot.ts	71
summary.FitAR	72

Index

73

AR1Est	<i>Exact MLE Mean-Zero AR(1)</i>
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Description

This function is used by GetFitAR in the AR(1) case. It is a fast exact solution using the root of a cubic equation.

Usage

```
AR1Est(z, MeanValue = 0)
```

Arguments

z	time series or vector
MeanValue	known mean

Details

The exact MLE for mean-zero AR(1) satisfies a cubic equation. The solution of this equation for the MLE given by Ying (2002) is used. This approach is more reliable as well as faster than the usual approach to the exact MLE using a numerical optimization technique which can occasionally have convergence problems.

Value

MLE for the parameter

Author(s)

A.I. McLeod and Ying Zhang

References

Zhang, Y. (2002). Topics in Autoregression, Ph.D. Thesis, University of Western Ontario.

See Also

[GetFitAR](#)

Examples

```
AR1Est(lynx-mean(lynx))
```

ARSdf

*Autoregressive Spectral Density Function***Description**

Spectral density function is computed.

Usage

```
ARSdf(phi, pFFT = 8)
```

Arguments

phi	AR Coefficients
pFFT	FFT with $2^p FFF$ frequencies, default 8

Details

The Fast Fourier Transform (FFT) is used to compute the spectral density function.

Value

A vector of the density function values, $(f(1), \dots, f(2^p FFF))$

Author(s)

A.I. McLeod

See Also

[spectrum](#), [spec.pgram](#), [spec.ar](#)

Examples

```
ARSdf(0.8)
```

ARToMA

*Coefficients in Infinite Moving Average Expansion***Description**

A stationary-causal AR(p) can be written as a general linear process (GLP). This function obtains the moving-average expansion out to the L -th lag, $z[t] = a[t] + \psi[1]*a[t-1] + \dots + \psi[L]*a[t-L]$.

Usage

```
ARToMA(phi, lag.max)
```

Arguments

phi	AR Coefficients
lag.max	maximum lag

Details

The coefficients are computed recursively as indicated in Box and Jenkins (1970).

Value

vector of length L+1 containing, (1,psi[1],...,psi[L])

Author(s)

A.I. McLeod

References

Box and Jenkins (1970), Time Series Analysis, Forecasting & Control

See Also

[InvertibleQ](#)

Examples

```
ARToMA(0.5, 20)
```

ARToPacf

Reparametrize AR coefficients in Terms of PACF

Description

Transform AR parameter coefficients into partial autocorrelation function (PACF).

Usage

```
ARToPacf(phi)
```

Arguments

phi	vector of AR parameter coefficients
-----	-------------------------------------

Details

For details see McLeod and Zhang (2006).

Value

Vector of length(phi) containing the parameters in the transformed PACF domain

Warning

No check for invertibility is done for maximum computational efficiency since this function is used extensively in the numerical optimization of the AR loglikelihood function in FitAR. Use InvertibleQ to test for invertible AR coefficients.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[InvertibleQ](#), [PacfToAR](#)

Examples

```
somePACF<-c(0.5,0.6,0.7,0.8,-0.9,-0.8)
#PacfToAR() transforms PACF to AR parameter coefficients.
someAR<-PacfToAR(somePACF)
test<-ARToPacf(someAR)
#This should be very small
sum(abs(test-somePACF))
```

AcfPlot

Autocorrelation Plot

Description

Produces correlation plot

Usage

```
AcfPlot(g, LagZeroQ= TRUE, ylab=NULL, main=NULL, ...)
```

Arguments

<i>g</i>	vector of autocorrelations at lags 1,...,length(<i>g</i>)
<i>LagZeroQ</i>	start plot at lag zero with <i>g</i> [0]=1
<i>ylab</i>	vertical axis label
<i>main</i>	plot title
...	optional graphical parameters

Value

No value. Plot is produced via plot function.

Author(s)

A.I. McLeod

See Also

[acf](#)

Examples

```
#  
#simple example, plot acf for AR(1)  
phi<-0.8  
maxLag<-20  
g<-phi^(1:maxLag)  
AcfPlot(g)  
AcfPlot(g, LagZeroQ=FALSE)  
#  
# Plot the sample inverse partial autocorrelations.  
# On the basis of this plot, Cleveland (1972) suggested an ARp(1,2,7)  
# for this data  
"InverseAcf" <-  
function(z, p=15){  
g<-TacfMA(GetFitAR(z-mean(z),1:p)$phiHat, lag.max=p)  
g/g[1]  
}  
#  
data(SeriesA)  
AcfPlot(InverseAcf(SeriesA), LagZeroQ=FALSE)
```

BackcastResidualsAR

*Innovation Residuals in AR***Description**

Obtains the residuals (estimated innovations). The residuals for $t=1,\dots,p$ are obtained using the backforecasting algorithm of Box and Jenkins (1970).

Usage

```
BackcastResidualsAR(y, phi, Q = 100, demean=TRUE)
```

Arguments

y	a time series or vector
phi	AR coefficients, lags 1,...,p
Q	for backcasting, the AR is approximated by an MA(Q)
demean	subtract sample mean

Details

The backforecasting algorithm is described in detail in the book of Box and Jenkins. The idea is to expected value of the innovation assuming a high-order MA(q).

Value

Vector of residuals

Note

No check is done that the AR is causal-stationary.

Author(s)

A.I. McLeod

References

Box and Jenkins (1970). Time Series Analysis: Forecasting and Control.

See Also

[InvertibleQ](#), [FitAR](#)

Examples

```
#compare residuals obtained using backcasting with fitted parameters and
# the residuals extracted from output of FitAR. They are identical.
p<-11
out<-FitAR(log(lynx), p)
phi<-out$phiHat #fitted parameters
resphi<-BackcastResidualsAR(log(lynx), phi)
sum(abs(resphi-resid(out)))
```

Boot.FitAR

Simulate a Fitted AR

Description

Simulate a realization from a fitted AR model. This is useful in the parametric bootstrap. Generic function for "Boot" method.

Usage

```
## S3 method for class 'FitAR':
Boot(obj, R=1, ...)
```

Arguments

obj	the output from FitAR
R	number of bootstrap replications
...	optional arguments

Value

A simulated time series with the same length as the original fitted time series is produced.

Author(s)

A.I. McLeod

See Also

[Boot](#) [SimulateGaussianAR](#)

Examples

```
#Plot log(lynx) time series and simulation
#
data(lynx)
ans <- FitAR(log(lynx), 8)
z<-Boot.FitAR(ans)
par(mfrow=c(2,1))
TimeSeriesPlot(log(lynx))
title(main="log(lynx) time series")
TimeSeriesPlot(z)
title(main="Simulated AR(8), fitted to log lynx")
#par(mfrow=c(1,1)
#
#Use bootstrap to compute standard errors of parameters
#takes about 18 seconds on a 3.6 GHz PC
ptm <- proc.time() #user time
R<-100 #number of bootstrap iterations
p<-c(1,2,4,7,10,11)
ans<-FitAR(log(lynx),p)
out<-Boot(ans, R)
fn<-function(z) FitAR(z,p)$zetaHat
sdBoot<-sqrt(diag(var(t(apply(out,fn,MARGIN=2))))) )
sdLargeSample<-coef(ans)[,2][1:6]
sd<-matrix(c(sdBoot,sdLargeSample),ncol=2)
dimnames(sd)<-list(names(sdLargeSample),c("Bootstrap","LargeSample"))
ptm<-(proc.time()-ptm)[1]
sd
```

Boot

Generic Bootstrap Function

Description

Generic function to bootstrap a fitted model.

Usage

`Boot(obj, R=1, ...)`

Arguments

<code>obj</code>	fitted object
<code>R</code>	number of bootstrap replicates
<code>...</code>	optional arguments

Details

At present, the only function implemented is [Boot.FitAR](#).

Value

Parametric bootstrap simulation

Author(s)

A.I. McLeod

See Also

[Boot.FitAR](#)

Examples

```
data(SeriesA)
out<-FitARLS(SeriesA, c(1,2,7))
Boot(out)
```

Boot.ts

Parametric Time Series Bootstrap

Description

An AR(p) model is fit to the time series using the AIC and then it is simulated.

Usage

```
Boot.ts(obj, R=1, ...)
```

Arguments

obj	a time series, class "ts"
R	number of bootstrap replicates
...	optional arguments

Value

A time series or vector.

Note

Parametric and nonparametric time series bootstraps are discussed by Davison and Hinkley (1997, Ch.8.2).

Author(s)

A.I. McLeod

References

Davison, A.C. and Hinkley, D.V. (1997), Bootstrap Methods and Their Application. Cambridge University Press.

See Also

[Boot.FitAR](#). Nonparametric bootstrap for time series is available in the function `tsboot` in the library `boot`.

Examples

```
data(SeriesA)
layout(matrix(c(1,2,1,2),ncol=2))
TimeSeriesPlot(SeriesA)
TimeSeriesPlot(Boot(SeriesA),main="Bootstrap of Series A")
```

BoxCox.Arima

Box-Cox Analysis for "Arima" Objects

Description

Implements Box-Cox analysis for "Arima" class objects, the output from `arima`. Variance change in time series is an important topic. In some cases using a Box-Cox transformation will provide a much simpler analysis than the much more complex ARMA-GARCH approach. See US Tobacco series example given below for an example.

Usage

```
## S3 method for class 'Arima':
BoxCox(object, interval = c(-1, 1), type = "BoxCox", InitLambda = "none", ...)
```

Arguments

<code>object</code>	output from <code>arima</code>
<code>interval</code>	interval to be searched for optimal transformation
<code>type</code>	Ignored unless, <code>InitLambda!="none"</code> . Type of transformation, default is "Box-Cox". Otherwise a simple power transformation.
<code>InitLambda</code>	default "none". Otherwise a numerical value giving the transformation parameter.
<code>...</code>	optional arguments passed to optimize

Details

If no transformation is used on the data, then the original data is used. But if a transformation has already been used, we need to inverse transform the data to recover the untransformed data.

For $\lambda \neq 0$, the Box-Cox transformation is of x is $(x - 1)^\lambda / \lambda$ whereas the regular power transformation is simply x^λ . When $\lambda = 0$, it is \log in both cases.

The log of the Jacobian is $(\lambda - 1) \sum_{t=D+1}^n \log(z_t) (\lambda - 1) * \text{sum}(\log(z[(D+1):n]))$, where λ is the transformation, $n=\text{length}(z)$, z is the vector of data and $D = d + ds*s$, where d is the degree of regular differencing, ds is the degree of seasonal differencing and s is the seasonal period. The

correct expression for the loglikelihood function was first given in Hipel and McLeod (1977, eqn. 10). Using the wrong expression for the Jacobian has a disastrous effect in many situations. For example with the international airline passenger time series, the MLE for lambda would be about 1.958 instead of close to zero.

If the minimum data value is ≤ 0 , a small positive constant, equal to the negative of the minimum plus 0.25, is added to all the data values.

Value

No value returned. Graphical output produced as side-effect. The plot shows relative likelihood function as well as the MLE and a confidence interval.

Note

The MASS package has a similar function `boxcox` but this is implemented only for regression and analysis of variance.

Author(s)

A.I. McLeod

References

Hipel, K.W. and McLeod, A.I. (1977). Advances in Box-Jenkins Modelling. Part 1, Model Construction. Water Resources Research 13, 567-575.

See Also

`arima`, `BoxCox`, `BoxCox.FitAR`

Examples

```
#Tobacco Production
data(USTobacco)
plot(USTobacco)
win.graph()
USTobacco.arima<-arima(USTobacco,order=c(0,1,1))
BoxCox(USTobacco.arima)
#
air.arima<-arima(AirPassengers, c(0,1,1), seasonal=list(order=c(0,1,1), period=12))
BoxCox(air.arima)
#
#In this example, we fit a model to the square-root of the sunspots and
#back transform in BoxCox.
sqrtsun.arima<-arima(sqrt(sunspot.year),c(2,0,0))
BoxCox(sqrtsun.arima, InitLambda=0.5, type="power")
#
#Back transform with AirPassengers
Garima<-arima(log(AirPassengers), c(0,1,1), seasonal=list(order=c(0,1,1),period=12))
BoxCox(Garima, InitLambda=0)
```

BoxCox.FitAR	<i>Box-Cox Analysis for "FitAR" Objects</i>
--------------	---

Description

This is a methods function to do a Box-Cox analysis for models fit using FitAR and FitARLS.

Usage

```
## S3 method for class 'FitAR':
BoxCox(object, interval = c(-1, 1), type = "BoxCox", InitLambda = "none", ...)
```

Arguments

object	output from FitAR or FitARLS
interval	interval to be searched for optimal transformation
type	Ignored unless, InitLambda!="none". Type of transformation, default is "Box-Cox". Otherwise a simple power transformation.
InitLambda	default "none". Otherwise a numerical value giving the transformation parameter.
...	optional arguments passed to optimize

Details

If no transformation is used on the data, then the original data is used. But if a transformation has already been used, we need to inverse transform the data to recover the untransformed data.

For $\lambda \neq 0$, the Box-Cox transformation is of x is $(x - 1)^\lambda / \lambda$ whereas the regular power transformation is simply x^λ . When $\lambda = 0$, it is log in both cases.

If the minimum data value is ≤ 0 , a small positive constant, equal to the negative of the minimum plus 0.25, is added to all the data values.

Value

No value returned. Graphical output produced as side-effect. The plot shows relative likelihood function as well as the MLE and a confidence interval.

Note

The MASS package has a similar function `boxcox` but this is implemented only for regression and analysis of variance.

Author(s)

A.I. McLeod

References

- Box, G. E. P. and Cox, D. R. (1964) An analysis of transformations. *Journal of Royal Statistical Society, Series B*, vol. 26, pp. 211-246.
- McLeod, A.I. and Zhang, Y. (2006a). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.
- McLeod, A.I. and Zhang, Y. (2006b, under review). Subset Autoregression Modelling. *Journal of Statistical Software*.

See Also

[BoxCox](#), [BoxCox.Arima](#)

Examples

```
#lynx time series. ARp subset model.
out<-FitARLS(lynx, c(1,2,4,10,11))
BoxCox(out)
#
#sunspots. ARz subset model.
z<-sunspot.year+0.25
p<-SelectModel(z, SubsetModel="z", lag.max=25, Best=1)
out<-FitAR(z, p)
BoxCox(out)
#
#compare with AR(10)
z<-sunspot.year+0.25
out<-FitAR(z, 10)
BoxCox(out)
#
#Back transform after fitting model to log(lynx)
p<-SelectModel(log(lynx),SubsetModel="z",Best=1)
ans<-FitAR(log(lynx), p)
BoxCox(ans, InitLambda=0)
#
#again with ARp subset model
p<-SelectModel(log(lynx),SubsetModel="p",Best=1)
ans<-FitARLS(log(lynx), p)
BoxCox(ans, InitLambda=0)
```

Description

Generic function

Usage

`BoxCox(object, ...)`

Arguments

object	model object
...	optional arguments

Value

No value returned. Graphical output produced as side-effect. The plot shows relative likelihood function as well as the MLE and a confidence interval.

Note

The MASS package has a similar function boxcox but this is implemented only for regression and analysis of variance.

Author(s)

A.I. McLeod

See Also

[BoxCox.Arima](#), [BoxCox.FitAR](#), [BoxCox.ts](#), [BoxCox.numeric](#)

Examples

```
BoxCox(lynx)
out<-FitARLS(lynx, c(1,2,4,10,11))
BoxCox(out)
out<-FitAR(lynx, c(1,2,4,5,7,8,10,11,12))
BoxCox(out)
```

BoxCox.numeric

Box-Cox Analysis for a Time Series

Description

An AR(p) model is selected using AIC and then the best Box-Cox transformation is determined. Requires package FitAR.

Usage

```
BoxCox.numeric(object, interval = c(-1, 1), IIDQ = FALSE, ...)
```

Arguments

object	a vector of time series values
interval	interval to be searched
IIDQ	If true, IID is assumed, ie. p=0. If FALSE, AR(p) is fit with p determined using AIC.
...	optional arguments

Details

If the minimum data value is ≤ 0 , a small positive constant, equal to the negative of the minimum plus 0.25, is added to all the data values. If $\text{length}(\text{object}) < 20$, no AR model is used, that is, $p=0$.

Value

No value returned. Graphical output produced as side-effect. The plot shows relative likelihood function as well as the MLE and a confidence interval.

Note

The MASS package has a similar function `boxcox` but this is implemented only for regression and analysis of variance.

Author(s)

A.I. McLeod

References

Box, G. E. P. and Cox, D. R. (1964) An analysis of transformations. *Journal of Royal Statistical Society, Series B*, vol. 26, pp. 211-246.

See Also

[BoxCox.FitAR](#), [BoxCox.Arima](#), [BoxCox.ts](#)

Examples

```
#  
#annual sunspot series  
BoxCox(sunspot.year, IIDQ=FALSE)  
#  
#non-time series example, lengths of rivers  
BoxCox(rivers)
```

Description

The time series is converted to a vector and `BoxCox.numeric` is used.

Usage

```
BoxCox.ts(object, interval = c(-1, 1), ...)
```

Arguments

<code>object</code>	a vector of time series values
<code>interval</code>	interval to be searched
<code>...</code>	optional arguments

Details

If the minimum data value is ≤ 0 , a small positive constant, equal to the negative of the minimum plus 0.25, is added to all the data values.

Value

No value returned. Graphical output produced as side-effect. The plot shows relative likelihood function as well as the MLE and a confidence interval.

Warning

It is important not to transform the data when fitting it with AR since the optimal transformation would be found for the transformed data – not the original data. Normally this would not be a sensible thing to do.

Note

The MASS package has a similar function `boxcox` but this is implemented only for regression and analysis of variance.

Author(s)

A.I. McLeod

References

Box, G. E. P. and Cox, D. R. (1964) An analysis of transformations. Journal of Royal Statistical Society, Series B, vol. 26, pp. 211-246.

See Also

`BoxCox.FitAR`, `BoxCox.Arima`, `BoxCox.numeric`

Examples

```
#  
BoxCox(sunspot.year)
```

Description

Computes sufficient statistics for AR

Usage

```
ChampernowneD(z, p, MeanZero = FALSE)
```

Arguments

<code>z</code>	time series data
<code>p</code>	order of the AR
<code>MeanZero</code>	Assume mean is zero. Default is FALSE so the sample mean is subtracted from the data first. Otherwise no sample mean correction is made.

Details

This matrix D is defined in McLeod & Zhang (2006)

Value

The matrix D defined following eqn. (3) of McLeod & Zhang (2006) is computed.

Note

This function is used by GetFitAR. It may be used to compute the exact loglikelihood for an AR.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. Journal of Time Series Analysis, 27, 599-612.

See Also

[GetFitAR](#), [FastLoglikelihoodAR](#), [FitAR](#)

Examples

```
#compute the exact concentrated loglikelihood function, (McLeod & Zhang, 2006, eq.(6)),
# for AR(p) fitted by Yule-Walker to logged lynx data
#
p<-8
CD<-ChampernowneD(log(lynx), p)
n<-length(lynx)
phi<-ar(log(lynx), order.max=p, aic=FALSE, method="yule-walker")$ar
LogLYW<-FastLoglikelihoodAR(phi,n,CD)
phi<-ar(log(lynx), order.max=p, aic=FALSE, method="burg")$ar
LoglBurg<-FastLoglikelihoodAR(phi,n,CD)
phi<-ar(log(lynx), order.max=p, aic=FALSE, method="ols")$ar
LoglOLS<-FastLoglikelihoodAR(phi,n,CD)
phi<-ar(log(lynx), order.max=p, aic=FALSE, method="mle")$ar
LoglMLE<-FastLoglikelihoodAR(phi,n,CD)
ans<-c(LogLYW,LoglBurg,LoglOLS,LoglMLE)
names(ans)<-c("YW","Burg","OLS","MLE")
ans
#compare the MLE result given by ar with that given by FitAR
FitAR(log(lynx),p)
```

DetAR	<i>Covariance Determinant of AR(p)</i>
-------	---

Description

Computes the covariance determinant of p successive observations from an AR(p) process with unit innovation variance.

Usage

```
DetAR(phi)
```

Arguments

phi vector of AR coefficients

Details

The AR coefficients are transformed to PACF and then the determinant is computed as a product of PACF terms as given in McLeod and Zhang (2006, eqn. 4).

Value

Determinant

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[FastLoglikelihoodAR](#)

Examples

```
DetAR(c(0.1, 0.1, 0.1))
```

FastLoglikelihoodAR*Fast Computation of the Loglikelihood Function in AR***Description**

Computation of the loglikelihood is O(1) flops in repeated evaluations of the loglikelihood holding the data fixed and varying the parameters. This is useful in exact MLE estimation.

Usage

```
FastLoglikelihoodAR(phi, n, CD)
```

Arguments

phi	AR coefficients
n	length of series
CD	Champernowne matrix

Details

The details of this computation are described in McLeod and Zhang (2006).

Value

loglikelihood

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[ChampernowneD](#), [LoglikelihoodAR](#)

Examples

```
#Compute the loglikelihood using the direct method as implemented
# in LoglikelihoodAR and using the fast method
data(SeriesA)
phi<-PacfToAR(rep(0.5,10))
p<-length(phi)
z<-SeriesA-mean(SeriesA)
n<-length(z)
L1<-LoglikelihoodAR(phi, z)
cd<-ChampernowneD(z,p,MeanZero=TRUE)
L2<-FastLoglikelihoodAR(phi,n,cd)
```

```

out<-c(L1,L2)
names(out)<-c("direct","fast")
out

```

FitAR

Exact MLE for AR(p) and Subset AR

Description

The estimation algorithm in McLeod & Zhang (2006a) is implemented.

Usage

```
FitAR(z, p, SubsetQ=FALSE, demean = TRUE, MeanMLEQ = FALSE, lag.max = "default")
```

Arguments

<code>z</code>	time series, vector or ts object.
<code>p</code>	<code>p</code> specifies the model. If <code>length(p)</code> is 1, an AR(<code>p</code>) is assumed and if <code>p</code> has length greater than 1, an AR <code>p</code> subset model with lags indicated by <code>p</code> is assumed. If you wish to fit a subset model with only one lag, say for example, 4, then set <code>p</code> to be <code>c(0,0,0,4)</code> . For <code>p=0</code> , white noise model.
<code>SubsetQ</code>	default FALSE. Ignored if <code>p</code> has length > 1. Need set to TRUE for ambiguous cases – see Note.
<code>demean</code>	if True, subtract mean. Otherwise assume it is zero.
<code>MeanMLEQ</code>	if True, an iterative algorithm is used for exact simultaneous MLE estimation of the mean and other parameters.
<code>lag.max</code>	the residual autocorrelations are tabulated for lags 1, ..., <code>lag.max</code> . Also <code>lag.max</code> is used for the Ljung-Box portmanteau test.

Details

The exact MLE for AR(`p`) and subset AR(`p`) are using methods described in McLeod and Zhang (2006a). In addition the exact MLE for the mean can be computed using an iterative backfitting approach described in McLeod and Zhang (2006b).

The default for `lag.max` is `ceiling(min(length(z)/4, min(max(length(z)/4, 30), 100)))`.

Value

A list with class name "FitAR" and components:

<code>loglikelihood</code>	value of the loglikelihood
<code>phiHat</code>	coefficients in AR(<code>p</code>) – including 0's
<code>sigsqHat</code>	innovation variance estimate
<code>muHat</code>	estimate of the mean
<code>covHat</code>	covariance matrix of the coefficient estimates
<code>zetaHat</code>	transformed parameters, <code>length(zetaHat)=# coefficients estimated</code>

RacfMatrix	residual autocorrelations and sd for lags 1...lag.max
LjungBox	table of Ljung-Box portmanteau test statistics
SubsetQ	parameters in AR(p) – including 0's
res	innovation residuals, same length as z
fits	fitted values, same length as z
lags	lags used in AR model
demean	TRUE if mean estimated otherwise assumed zero
FitMethod	"MLE" for this function
IterationCount	number of iterations in mean mle estimation
convergence	value returned by optim – should be 0
MLEMeanQ	TRUE if mle for mean algorithm used
tsp	tsp(z)
call	result from match.call() showing how the function was called
ModelTitle	description of model
DataTitle	returns attr(z,"title")

Note

The SubsetQ parameter is used to distinguish models such as seasonal lag models from full AR models. For large p, this algorithm is faster than the built-in R function. See example below. There are generic print, summary, coef and resid functions for class "FitAR".

Author(s)

A.I. McLeod

References

- McLeod, A.I. and Zhang, Y. (2006a). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.
- McLeod, A.I. and Zhang, Y. (2006b, Accepted). Faster ARMA Maximum Likelihood Estimation, *Computational Statistics and Data Analysis*.

See Also

[FitARLS](#), [RacfPlot](#)

Examples

```
#First Example: Fit exact MLE to AR(4) using FitAR and arima
set.seed(3323)
phi<-c(2.7607,-3.8106,2.6535,-0.9238)
z<-SimulateGaussianAR(phi,1000)
ans1<-arima(z, order=c(4,0,0))
ans2<-FitAR(z, 4, MeanMLEQ=TRUE)
ans1
coef(ans2)

#Second Example: compare with sample mean result
```

```

ans3<-FitAR(z, 4)
coef(ans3)

#Third Example: Fit subset AR model to lynx series
z<-log(lynx)
FitAR(z, c(1,2,4,7,10,11))
#now obtain exact MLE for Mean as well
FitAR(z, c(1,2,4,7,10,11), MeanMLE=TRUE)

#Fourth Example: Some Timings
t1<-system.time(ans1<-ar(sunspot.month, order.max=25, aic=FALSE, method="mle"))[[1]]
t2<-system.time(ans2<-FitAR(sunspot.month, 25))[[1]]
#uncomment lines below to run full examples but it takes about
# 4 minutes on a 3.6GHz PC
#
#t3<-system.time(ans3<-FitAR(sunspot.month, 25, MeanMLE=TRUE) ) [[1]]
#times<-c(t1,t2,t3)
#names(times)<-c("ar","FitAR", "FitAR-MeanMLE")

```

FitARLS*Fit Subset AR Using OLS***Description**

The usual subset AR model is defined by selecting a subset of the AR coefficients and setting all other coefficients to zero. This subset model is fit using least squares.

Usage

```
FitARLS(z, p, SubsetQ = FALSE, lag.max = "default")
```

Arguments

<code>z</code>	time series
<code>p</code>	Vector specifying which lags to use in the AR. If <code>SubsetQ=FALSE</code> , <code>p</code> should be a scalar and a regular AR(<code>p</code>) will be fit. For <code>p=0</code> , white noise.
<code>SubsetQ</code>	default <code>FALSE</code> . Ignored if <code>p</code> has length > 1. Need set to <code>TRUE</code> for ambiguous cases – see Note.
<code>lag.max</code>	The maximum lag to be used in the Portmanteau Test

Details

The design matrix, X , is formed by concatenating together the needed columns and then the R function `lsfit` is used. An intercept term is used with `lsfit`. The residuals are computed using `BackcastResidualsAR`. The exact loglikelihood is computed using `LoglikelihoodAR`.

Value

A list with class name "FitAR" and components:

loglikelihood	value of the loglikelihood using LoglikelihoodAR
phiHat	coefficients in AR(p) – including 0's
sigsqHat	innovation variance estimate
muHat	estimate of the mean
covHat	covariance matrix of the coefficient estimates
zetaHat	transformed parameters, length(zetaHat)=# coefficients estimated
RacfMatrix	residual autocorrelations and sd for lags 1...lag.max
LjungBox	table of Ljung-Box portmanteau test statistics
SubsetQ	parameters in AR(p) – including 0's
res	innovation residuals, same length as z
fits	fitted values, same length as z
lags	lags used in AR model
demean	TRUE if mean estimated otherwise assumed zero
FitMethod	"LS" for this function
tsp	tsp(z)
call	result from match.call() showing how the function was called
yX	the dependent variable column prepended to the columns of independent variables
ModelTitle	description of model
DataTitle	returns attr(z,"title")

Note

If SubsetQ=FALSE, this is equivalent to the built-in function ar(..., method="OLS"). Note that least-squares residuals are not used. The residuals are calculated using BackcastResidualsAR and the loglikelihood is calculated using LoglikelihoodAR.

Author(s)

A.I. McLeod

References

Tong, H. (1977). Some comments on the Canadian lynx data. Journal of the Royal Statistical Society A 140, 432-436.

See Also

[FitAR](#), [LoglikelihoodAR](#), [BackcastResidualsAR](#), [ar](#)

Examples

```
#Compare the fit achieved by the two types of subset models
z<-log(lynx)
pvec<-SelectModel(z, SubsetModel="z", Criterion="BIC", lag.max=12, Best=1)
pvec
FitARLS(z, pvec)
FitAR(z, pvec)
```

FromSymmetricStorageUpper

Converts a Matrix from Symmetric Storage Mode to Regular Format

Description

Utility function.

Usage

```
FromSymmetricStorageUpper (x)
```

Arguments

x	a vector which represents a matrix in upper triangular form
---	---

Value

symmetric matrix

Author(s)

A.I. McLeod

Examples

```
FromSymmetricStorageUpper (1:5)
```

Get1G

Internal Utility Function: BLUE mean

Description

This function is not normally used directly by the user. It is used in the exact mle for mean.

Usage

```
Get1G(phi, n)
```

Arguments

phi	vector of AR coefficients
n	length of series

Details**Value**

A vector used in the mle computation of the mean

Author(s)

A.I. McLeod

See Also

[GetARMeanMLE](#)

Examples

```
#Simulate an AR(2) and compute the exact mle for mean
set.seed(7771111)
n<-50
phi<-c(1.8,-0.9)
z<-SimulateGaussianAR(phi, n)
g1<-Get1G(phi, length(z))
sum(g1*z)/sum(g1)
#sample mean
mean(z)
#more directly with getArMu
GetARMeanMLE(z,phi)
```

`GetARMeanMLE`

Exact MLE for Mean in AR(p)

Description

Details of this algorithm are given in McLeod and Zhang (2007).

Usage

`GetARMeanMLE(z, phi)`

Arguments

<code>z</code>	vector of length n containing the time series
<code>phi</code>	vector of AR coefficients

Value

Estimate of mean

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[mean](#)

Examples

```
#Simulate a time series with mean zero and compute the exact
#mle for mean and compare with sample average.
set.seed(3323)
phi<-c(2.7607,-3.8106,2.6535,-0.9238)
z<-SimulateGaussianAR(phi,1000)
ans1<-mean(z)
ans2<-GetARMeanMLE(z,phi)
# define a direct MLE function
"DirectGetMeanMLE" <-
function(z, phi){
  GInv<-solve(toeplitz(TacfAR(z, length(z)-1)))
  g1<-colSums(GInv)
  sum(g1*z)/sum(g1)
}
ans3<-DirectGetMeanMLE(z,phi)
ans<-c(ans1,ans2,ans3)
names(ans)<-c("mean", "GetARMeanMLE", "DirectGetMeanMLE")
ans
```

Description

The user would not normally use this function. The function is needed for exact mle for mean. Used in Get1G which is called from GetARMeanMLE.

Usage

GetB (phi)

Arguments

phi	vector of AR coefficients
-----	---------------------------

GetFitAR

*Fit AR(p)***Description**

Obtains the exact MLE for AR(p) or subset AR model. This function is used by FitAR. One might prefer to use GetFitAR for applications such as bootstrapping since it is faster than FitAR.

Usage

```
GetFitAR(z, pvec, MeanValue=0, ...)
```

Arguments

<code>z</code>	time series
<code>pvec</code>	lags included in AR model. If <code>pvec=0</code> , white noise model assumed.
<code>MeanValue</code>	by default it is assumed the mean of <code>z</code> is 0
<code>...</code>	optional arguments passed through to optim

Details

The built-in function `optim` is used to obtain the MLE estimates for an AR or subset AR.

Value

<code>loglikelihoold</code>	value of maximized loglikelihood
<code>zetaHat</code>	estimated zeta parameters
<code>phiHat</code>	estimated phi parameters
<code>convergence</code>	result from <code>optim</code>

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[FitAR](#)

Examples

```
#compare results from GetFitAR and FitAR
z<-log(lynx)
z<-z - mean(z)
GetFitAR(z, c(1,2,8))
out<-FitAR(log(lynx), c(1,2,8))
out
coef(out)
```

Description

For AR_p subset models, the least squares estimates are computed. The exact loglikelihood is then determined. The estimated parameters are checked to see if they are in the AR admissible region.

Usage

```
GetFitARLS(z, pvec)
```

Arguments

<code>z</code>	vector or ts object, the time series
<code>pvec</code>	lags included in subset AR. If <code>pvec=0</code> , white noise assumed.

Details

The R function `lsfit` is used.

Value

a list with components:

<code>loglikelihood</code>	the exact loglikelihood
<code>phiHat</code>	estimated AR parameters
<code>constantTerm</code>	constant term in the linear regression
<code>lags</code>	estimated AR parameters
<code>res</code>	the least squares regression residuals
<code>yX</code>	the dependent variable column prepended to the columns of independent variables
<code>InvertibleQ</code>	True, if the estimated parameters are in the AR admissible region.

Note

This is a helper function for `FitARLS`. Normally the user would `FitARLS` since this function provides generic print, summary, resid and plot methods but `GetFitARLS` is sometimes useful in iterative computations like bootstrapping since it is faster.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[FitARLS](#), [FitAR](#), [GetFitAR](#), [LoglikelihoodAR](#) [SelectModel](#)

Examples

```
#Fit subset AR using GetFitARLS and FitARLS
data(SeriesA)
ansLS<-GetFitARLS(SeriesA, c(1,2,7))
ans<-FitARLS(SeriesA, c(1,2,7))
ansLS
ans
summary(ans)
summary(resid(ans))
plot(ans)
```

GetKappa

*Internal Utility Function***Description**

Used by Get1G.

Usage

```
GetKappa(phi)
```

Arguments

phi	ARCoefficients
-----	----------------

GetLeapsAR

*Select lags for Best Subset AR_p Model***Description**

The subset AR_p model is the usual subset model, for example see Tong (1977). This function is used by SelectModel for model identification for AR_p models.

Usage

```
GetLeapsAR(z, lag.max = 15, Criterion = "UBIC", Best = 3, Candidates=5)
```

Arguments

z	ts object or vector containing time series
lag.max	maximum order of the AR
Criterion	default UBIC, other choices are "AIC" or "BIC"
Best	the number of based selected based on highest AIC/BIC
Candidates	number of models initially selected using the approximate criterion

Details

The R function leaps in the R package leaps is used to compute the subset regression model with the smallest residual sum of squares containing 1,...,lag.max parameters. The mean is always included, so the only parameters considered are the phi coefficients. After the best models containing 1,...,lag.max parameters are selected the models are individually refit using GetFitARLS to determine the exact likelihood function for each selected model. Based on this likelihood the UBIC/BIC/AIC is computed and then the best models are selected. The UBIC criterion was developed by Chen and Chen (2007).

Value

a list with components

NumParameters

UBIC

AIC

BIC

p

lags present

Warning

AIC and BIC values produced are not comparable to AIC and BIC produced by SelectModel for ARz models. However comparable AIC/BIC values are produced when the selected models are fit by FitARLS or FitAR respectively.

Note

Requires leaps package

Author(s)

A.I. McLeod

References

Tong, H. (1977) Some comments on the Canadian lynx data. Journal of the Royal Statistical Society A 140, 432-436.

Chen, J. and Chen, Z. (2007). Extended Bayesian Information Criteria for Model Selection with Large Model Space. Preprint.

See Also

[SelectModel](#), [GetFitARLS](#), [leaps](#)

Examples

```
#for the log(lynx) Tong (1977) selected an ARp(1,2,4,10,11)
#using the AIC and a subset selection algorithm. Our more exact
#approach shows that the ARp(1,2,3,4,10,11) has slightly lower
#AIC (using exact likelihood evaluation).
z<-log(lynx)
GetLeapsAR(z, lag.max=11)
GetLeapsAR(z, lag.max=11, Criterion="BIC")
```

InformationMatrixAR

Information Matrix for AR(p)

Description

The Fisher large-sample information matrix per observation for the p coefficients in an AR(p) is computed.

Usage

```
InformationMatrixAR(phi)
```

Arguments

phi	vector of length p corresponding to the AR(p) coefficients
-----	--

Details

The Fisher information matrix is computed as the covariance matrix of an AR(p) process with coefficients given in the argument phi and with unit innovation variance. The TacvfAR function is used to compute the necessary autocovariances. FitAR uses InformationMatrixAR to obtain estimates of the standard errors for the estimated parameters in the case of the full AR(p) model.

Value

a p-by-p Toeplitz matrix, p=length(phi)

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. Journal of Time Series Analysis, 27, 599-612.

See Also

[FitAR](#), [InformationMatrixARp](#), [TacvfAR](#), [InformationMatrixARz](#)

Examples

```
InformationMatrixAR(c(1.8,-0.6))
```

InformationMatrixARp
Information Matrix for ARp

Description

The large-sample information matrix per observation is computed in a subset AR with the usual parameterization, that is, a subset of the AR coefficients.

Usage

```
InformationMatrixARp(phi, lags)
```

Arguments

phi	vector of coefficients in the subset AR
lags	vector indicating lags present in phi

Details

The subset information matrix is obtained simply by selecting the appropriate rows and columns from the full information matrix. This function is used by `FitARLS` to obtain the estimated standard errors of the parameter estimates.

Value

a p-by-p Toeplitz matrix, p=length(phi)

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[InformationMatrixAR](#), [FitARLS](#), [InformationMatrixARz](#)

Examples

```
#variances of parameters in a subset ARp(1,2,6)
fi<-InformationMatrixARp(c(0.36,0.23,0.23),c(1,2,6))
sqrt(diag(solve(fi*197)))
```

InformationMatrixARz
Information Matrix AR z

Description

Computes the large-sample Fisher information matrix per observation for the AR coefficients in a subset AR when parameterized by the partial autocorrelations.

Usage

```
InformationMatrixARz(zeta, lags)
```

Arguments

<code>zeta</code>	vector of coefficients, ie. partial autocorrelations at lags specified in the argument <code>lags</code>
<code>lags</code>	lags in subset model, same length as <code>zeta</code> argument

Details

The details of the computation are given in McLeod and Zhang (2006, eqn 13). FitAR uses `InformationMatrixARz` to obtain estimates of the standard errors of the estimated parameters in the subset AR model when partial autocorrelation parameterization is used.

Value

a p-by-p Toeplitz matrix, p=length(`zeta`)

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[FitAR](#), [InformationMatrixAR](#), [InformationMatrixARp](#)

Examples

```
#Information matrix for ARz(1,4) with parameters 0.9 and 0.9.
InformationMatrixARz(c(0.9, 0.9), lags=c(1,4))
```

InvertibleQ

*Invertibility Test***Description**

Tests if the polynomial

$$1 - \phi(1)B - \phi(2)B^2 - \dots - \phi(p)B^p,$$

where p=length[phi] has all roots outside the unit circle. This is the invertibility condition for the polynomial.

Usage

```
InvertibleQ(phi)
```

Arguments

phi	a vector of AR coefficients
-----	-----------------------------

Details

The PACF is computed for lags 1,...,p using eqn. (1) in McLeod and Zhang (2006). The invertibility condition is satisfied if and only if all PACF values are less than 1 in absolute value.

Value

TRUE, if invertibility condition is satisfied. FALSE, if not invertible.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[ARToPacf](#)

Examples

```
#simple examples
InvertibleQ(0.5)
#find the area of the invertible region for AR(2).
#We assume that the parameters must be less than 2 in absolute value.
#From the well-known diagram in the book of Box and Jenkins (1970),
#this area is exactly 4.
NSIM<-10^4
phi1<-runif(NSIM, min=-2, max=2)
phi2<-runif(NSIM, min=-2, max=2)
k<-sum(apply(matrix(c(phi1,phi2),ncol=2), MARGIN=1, FUN=InvertibleQ))
area<-16*k/NSIM
area
```

Jacobian

Jacobian AR-coefficients to Partial Autocorrelations

Description

This is more or less and internal routine used by `InformationMatrixZeta` but it is described in more detail since it may be useful in other computations.

Usage

```
Jacobian(zeta)
```

Arguments

zeta	partial autocorrelation parameters
------	------------------------------------

Details

The computation is described in detail in McLeod and Zhang (2006, Section 2.2)

Value

square matrix of order `length(zeta)`

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[InformationMatrixARz](#)

Examples

```
# In McLeod and Zhang (2006, p.603) a symbolic example is given
# for the AR(4).
#
Jacobian(rep(0.8,4))
```

JacobianK	<i>Internal Utility Function</i>
-----------	----------------------------------

Description

The matrix defined in eqn. (10) of McLeod and Zhang (2006). Used by the function [Jacobian](#).

Usage

```
JacobianK(zeta, k)
```

Arguments

zeta	partial autocorrelations
k	k-th Jacobian

Value

matrix

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[Jacobian](#)

Examples

```
JacobianK(rep(0.8, 4), 3)
```

JarqueBeraTest	<i>Jarque-Bera Normality Test</i>
----------------	-----------------------------------

Description

A powerful omnibus test for normality.

Usage

```
JarqueBeraTest(z)
```

Arguments

z	vector of data
---	----------------

Details

This test is derived as a Lagrange multiplier test for normal distribution in the family of Pearson distributions (Jarque and Bera, 1987).

Value

LM	value of the LM statistic
pvalue	p-value

Author(s)

A.I. McLeod

References

Jarque, C.M. and Bera, A.K. (1987). A Test for Normality of Observations and Regression Residuals. International Statistical Review 55, 163-172

Examples

```
#some normal data
z<-rnorm(100)
JarqueBeraTest(z)
#some skewed data
z<-rexp(100)
JarqueBeraTest(z)
#some thick tailed data
z<-rt(100,5)
JarqueBeraTest(z)
```

LBQPlot

Plot Ljung-Box Test P-value vs Lag

Description

The Ljung-Box portmanteau p-value is plotted vs lag.

Usage

```
LBQPlot (obj, SquaredQ=FALSE)
```

Arguments

obj	output from FitAR or FitARLS
SquaredQ	default, SquaredQ=FALSE, regular autocorrelations. If SquaredQ=TRUE use autocorrelations of squared residuals.

Value

Plot is produced as a side-effect. No output

Note

This function is normally invoked when `plot.FitAR` is used.

Author(s)

A.I. McLeod

References

Ljung, G.M. and Box, G.E.P. (1978) On a measure of lack of fit in time series models. *Biometrika* 65, 297-303.

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

`plot.FitAR`, `FitAR`, `FitARLS`

Examples

```
#fit subset AR and plot diagnostic check
data(SeriesA)
out<-FitARLS(SeriesA, c(1,2,7))
LBQPlot(out)
#note that plot produces LBQPlot and RacfPlot
plot(out)
```

LjungBoxTest

Ljung-Box Test for Randomness

Description

The Ljung-Box Portmanteau test for the goodness of fit of ARIMA models is implemented.

Usage

```
LjungBoxTest(res, k=0, lag.max=30, StartLag=10, SquaredQ=FALSE)
```

Arguments

res	residuals
k	number of ARMA parameters, default k=0
lag.max	maximum lag, default MaxLag=30
StartLag	test is done for lags m=StartLag:MaxLag, default StartLag=10
SquaredQ	if TRUE, use squared residuals for ARCH test, default Squared=FALSE

Details

This test is described in detail in Wei (2006, p.153, eqn. 7.5.1).

Value

A matrix with columns labelled m, Qm, pvalue, where m is the lag and Qm is the Ljung-Box Portmanteau statistic and pvalue its p-value. A powerful test for ARCH and other nonlinearities is obtained by using squared values of the series to be tested (McLeod & Li, 1983). Note that if Squared=TRUE is used the data "res" is centered by sample mean correction before squaring.

Note

This test may also be used to test a time series for randomness taking k=0.

Author(s)

A.I. McLeod

References

- W.W.S. Wei (2006, 2nd Ed.), *Time Series Analysis: Univariate and Multivariate Methods*.
 A.I. McLeod. & W.K. Li (1983), Diagnostic checking ARMA time series models using squared-residual autocorrelations, *Journal of Time Series Analysis* **4**, 269–273.

See Also

[Box.test](#)

Examples

```
#test goodness-of-fit of AR(2) model fit to log(lynx)
data(lynx)
z<-log(lynx)
ans<-FitAR(z, 1:2)
#notice that the test is also available as a component of the output of FitAR (FitARLS also)
ans$LjungBox
#a plot of the test is produced
plot(ans)
#doing the test manually
res<-resid(ans)
LjungBoxTest(res, k=2, lag.max=20, StartLag=5)

#test for subset case
z<-log(lynx)
pvec<-SelectModel(z, SubsetModel="z", Criterion="BIC", lag.max=10, Best=1)
ans<-FitAR(z, pvec)
plot(ans)
res<-resid(ans)
LjungBoxTest(res, k=length(pvec), lag.max=20, StartLag=11)
#test for ARCH effect,
LjungBoxTest(res, SquaredQ=TRUE)
```

LoglikelihoodAR	<i>Exact Loglikelihood for AR</i>
-----------------	-----------------------------------

Description

The exact loglikelihood function, defined in eqn. (6) of McLeod & Zhang (2006) is computed. Requires O(n) flops, n=length(z).

Usage

```
LoglikelihoodAR(phi, z, MeanValue = 0)
```

Arguments

phi	AR parameters
z	time series data, not assumed mean corrected
MeanValue	usually this is mean(z) but it could be another value for example the MLE of the mean

Details

Eqn (6) of McLeod and Zhang (2006) may be written

$$-(n/2) \log(\hat{\sigma}_a^2) - (1/2) \log(g_p),$$

where $\hat{\sigma}_a^2$ is the residual variance and g_p is the covariance determinant.

Value

The value of the loglikelihood is returned

Warning

No check is done for stationary-causal process

Note

For MLE computation it is better to use [FastLoglikelihoodAR](#) since for repeated likelihood evaluations this requires only O(1) flops vs O(n) flops, where n=length(z).

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. Journal of Time Series Analysis, 27, 599-612.

See Also

[FastLoglikelihoodAR](#)

Examples

```
#Fit a subset model to Series A and verify the loglikelihood
data(SeriesA)
out<-FitAR(SeriesA, c(1,2,7))
out
#either using print.default(out) to see the components in out
#or applying LoglikelihooodAR () by first obtaining the phi parameters as out$phiHat.

#
LoglikelihooodAR(out$phiHat, SeriesA, MeanValue=mean(SeriesA))
```

Ninemile

Douglas Fir Treerings, Nine Mile Canyon, Utah, 1194-1964

Description

A treering time series comprises of 771 values showing a periodicity of around 10 years.

Usage

```
data(Ninemile)
```

Format

ts object with title attribute

Source

Hipel, K.W. and McLeod, A.I. (2006). Time Series Modelling of Water Resources and Environmental Systems.

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. Journal of Time Series Analysis, 27, 599-612.

Examples

```
data(Ninemile)
ans<-FitAR(Ninemile, c(1,2,9))
summary(ans)
```

Description

Given autocovariances, the partial autocorrelations and/or autoregressive coefficients in an AR may be determined using the Durbin-Levinson algorithm. If the autocovariances are sample autocovariances, this is equivalent to using the Yule-Walker equations. But as noted below our function is more general than the built-in R functions.

Usage

```
PacfDL(c, LinearPredictor = FALSE)
```

Arguments

c	autocovariances at lags 0,1,...,p=length(c)-1
LinearPredictor	if TRUE, AR coefficients are also determined using the Yule-Walker method

Details

The Durbin-Levinson algorithm is described in many books on time series and numerical methods, for example Percival and Walden (1993, eqn 403).

Value

If LinearPredictor=FALSE, vector of length p=length(c)-1 containing the partial autocorrelations at lags 1,...,p. Otherwise a list with components:

Pacf	vector of partial autocorrelations
ARCoefficients	vector of AR coefficients
ResidualVariance	residual variance for AR(p)

Warning

Stationarity is not tested.

Note

Sample partial autocorrelations can also be computed with the `acf` function and Yule-Walker estimates can be computed with the `ar` function. Our function `PacfDL` provides more flexibility since then input c may be any valid autocovariances not just the usual sample autocovariances. For example, we can determine the minimum mean square error one-step ahead linear predictor of order p for theoretical autocovariances from a fractional arma or other linear process.

Author(s)

A.I. McLeod

References

Percival, D.B. and Walden, A.T. (1993). Spectral Analysis For Physical Applications, Cambridge University Press.

See Also

[acf](#), [ar](#)

Examples

```
#first define a function to compute the Sample Autocovariances
sacvf<-function(z, lag.max){
  c(acf(z, plot=FALSE, lag.max=lag.max)$acf)*(length(z)-1)/length(z)
}
#now compute PACF and also fit AR(7) to SeriesA
data(SeriesA)
ck<-sacvf(SeriesA, 7)
PacfDL(ck)
PacfDL(ck, LinearPredictor = TRUE)
#compare with built-in functions
pacf(SeriesA, lag.max=7, plot=FALSE)
ar(SeriesA, lag.max=7, method="yw")
#fit an optimal linear predictor of order 10 to MA(1)
g<-TacfMMA(0.8,5)
PacfDL(g, LinearPredictor=TRUE)
#
#Compute the theoretical pacf for MA(1) and plot it
ck<-c(1,-0.4,rep(0,18))
AcfPlot(PacfDL(ck)$Pacf)
title(main="Pacf of MA(1), r(1)=-0.4")
```

PacfPlot

Plot Partial Autocorrelations and Limits

Description

The partial autocorrelations and their individual 95 percent confidence intervals are plotted under the assumption the model is contained in an AR(P), where P is a specified upper limit.

Usage

`PacfPlot(z, lag.max = 15, ...)`

Arguments

<code>z</code>	time series
<code>lag.max</code>	maximum lag, P
<code>...</code>	optional parameters passed through to plot.

Details

The Burg algorithm is used to estimate the PACF.

Value

No value is returned. Graphical output is produced as side-effect.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[ar.burg pacf](#)

Examples

```
#For the log(lynx) series and taking lag.max=15, the PacfPlot and
# the minimum BIC subset selection produce the same result.
z<-log(lynx)
PacfPlot(z)
SelectModel(z,lag.max=15,SubsetModel="z",Best=1,Criterion="BIC")
```

Description

Transforms AR partial autocorrelation function (PACF) parameters to AR coefficients based on the Durbin-Levinson recursion.

Usage

PacfToAR(zeta)

Arguments

zeta	vector of AR PACF parameters
------	------------------------------

Details

see Mcleod and Zhang (2006)

Value

vector of AR coefficients

Author(s)

A.I. McLeod

References

McLeod and Zhang (2006)

See Also

[InvertibleQ](#), [PacfToAR](#)

Examples

```
somePACF<-c(0.5,0.6,0.7,0.8,-0.9,-0.8)
someAR<-PacfToAR(somePACF)
test<-ARToPacf(someAR)
#this should be very small
sum(abs(test-somePACF))
```

PlotARSdf

Plot AR or ARMA Spectral Density

Description

Constructs a plot of the AR spectral density function

Usage

```
PlotARSdf(phi = NULL, theta = NULL, units = "radial", logSdf = FALSE, Innovation
```

Arguments

phi	AR Coefficients
theta	MA Coefficients
units	default is "radial"
logSdf	default is FALSE otherwise log sdf is plotted
InnovationVariance	innovation variance, default is 1
main	optional plot title
sub	optional subtitle
...	optional arguments

Details

The spectral density function is symmetric and defined in $(-\pi, \pi)$ but plotted over $(0, \pi)$. If units are not "radial", it is plotted over $(0, 0.5)$.

Value

No value. Plot is generated as product by using R plot.

See Also

[ARSdf](#)

Examples

```
#AR(1)
PlotARSdf(0.8)
#MA(1)
PlotARSdf(theta=0.8)
#ARMA(1,1)
PlotARSdf(0.9,0.5)
#white noise
PlotARSdf()
```

RacfPlot

Residual Autocorrelation Plot

Description

Residual autocorrelation plot for "FitAR" objects. This plot is useful for diagnostic checking models fit with the functions [FitAR](#) and [FitARLS](#)

Usage

```
RacfPlot(obj, lag.max = 1000, SquaredQ=FALSE)
```

Arguments

<code>obj</code>	output from FitAR or FitARLS
<code>lag.max</code>	maximum lag. Set to 1000 since minimum of this value and the value in the <code>obj</code> is used.
<code>SquaredQ</code>	default is FALSE. For squared residual autocorrelations, set to TRUE

Details

The standard deviations of the residual autocorrelations are obtained from McLeod (1978, eqn.16) or McLeod and Zhang (2006, eqn.16). Simultaneous confidence bounds are shown and constructed using the Bonferroni approximation as suggested by Hosking and Ravishanker (1993)

Value

Plot is produced as a side-effect. No output

Note

This function is normally invoked when `plot.FitAR` is used.

Author(s)

A.I. McLeod

References

- Hosking, J.R.M. and Ravishanker, N. (1993) Approximate simultaneous significance intervals for residual autocorrelations of autoregressive-moving average time series models. *Journal of Time Series Analysis* 14, 19-26.
- McLeod, A.I. (1978), On the distribution and applications of residual autocorrelations in Box-Jenkins modelling, *Journal of the Royal Statistical Society B* 40, 296-302.
- McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[plot.FitAR](#), [FitAR](#), [FitARLS](#)

Examples

```
#fit subset AR and plot diagnostic check
data(SeriesA)
out<-FitARLS(SeriesA, c(1,2,7))
RacfPlot(out)
#note that plot produces LBQPlot and RacfPlot
plot(out)
#check squared residuals
RacfPlot(out, SquaredQ=TRUE)
```

Description

This function inputs time series stored in ASCII in a format that the first line in the file is a title, next few lines, beginning with a #, are comments, and the remaining lines contain the data. Here is an example:

```
Changes In Global Temperature, Annual, 1880-1985
cr #Surface air "temperature change" for the globe, 1880-1985.
cr #Degrees Celsius. "Temperature change" actually means temperature
cr #Surface Air Temperature", 'Journal of Geophysical Research', Vol.
92,
cr -.40 -.37 -.43 ....
cr .....
cr .27 .42 .02 .30 .09 .05
cr
```

Usage

```
Readts(file = "", freq = 1, start = 1, VerboseQ=TRUE)
```

Arguments

file	location for input file
freq	tsp parameter, =1, annual, =12 monthly etc
start	tsp parameter
VerboseQ	normally prompt for arguments but set VerboseQ=FALSE to automate

Value

ts object with attribute 'title'

Author(s)

A.I. McLeod

See Also

[scan](#), [ts](#),

Examples

```
#You will need to change save the data given above in a file
#and change the directory as appropriate
#z<-Readts(file="d:/datasets/mhsets/annual/globtp.1", start=1880, VerboseQ=FALSE)
```

SelectModel

Select Best AR, ARz or ARp Model

Description

The AIC/BIC/UBIC criterion is used to select the best fitting AR or subset AR model. The result may be plotted using `plot`.

Usage

```
SelectModel(z, lag.max = 15, SubsetModel = c("n", "p", "z"), Criterion = "default")
```

Arguments

z	time series data
lag.max	maximum order of autoregression
SubsetModel	default is no subset, SubsetModel="n". Alternatives are ARp, SubsetModel="p" or ARz, SubsetModel="z"
Criterion	default is "UBIC". Options: "BIC" and "AIC".
Best	final number of models to be selected
Candidates	number of models initially selected using the approximate criterion

Details

McLeod and Zhang (2006) outline an approximate AIC/BIC selection algorithm. This algorithm is a refinement of that method. The refinement consists of automatically look for the best k candidates, where $k = \text{Candidates}$. Then the exact likelihood is evaluated for all k candidates. Out of these k candidates, the best $q = \text{Best}$ are then selected. This two-step procedure is needed because if k is too low, the approximate AIC/BIC rankings may not agree with the exact rankings. This strategy is used for model selection for AR, ARz and ARp models. A plot method is available to graph the output. The UBIC developed by Chen and Chen (2007) is an important extension of the BIC criterion for subset selection. In the non-subset case UBIC is equivalent to BIC.

Value

When $\text{Best} = 1$, a vector is returned indicated the lag or lags included in the model. The null model is indicated by returning 0 for the lag. An object with class "Selectmodel" is returned when $\text{Best} > 1$. If $\text{SubsetQ} = \text{FALSE}$, a matrix is return whose first column shows p and second AIC or BIC. Otherwise for subset selection, the result is a list with q components, where $q = \text{BEST}$. When Criterion="UBIC", the components in this list are:

p	lags present, a 0 indicates the null model
UBIC	exact UBIC

Similarly for the AIC/BIC case.

The components are arranged in order of the criterion used.

When $\text{SubsetModel} = \text{"p"}$ or "z" , an attribute "model" indicating "ARp" or "ARz" is included.

Warning

Setting Candidates too low can result in anomalous results. For example if Candidates=1, we find that the top ranking model may depend on how large Best is set. This phenomenon is due to the fact that among the best AIC/BIC models there is sometimes very little difference in their AIC/BIC scores. Since the initial ranking of the Candidates is done using the approximate likelihood, the final ranking using the exact likelihood may change.

Note

For white noise, the best model is the null model, containing no lags. This is indicating by setting the model order, $p = 0$.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

Chen, J. and Chen, Z. (2007). Extended Bayesian Information Criteria for Model Selection with Large Model Space. Preprint.

See Also

`plot.Selectmodel`, `PacfPlot`, `PacfPlot`, `FitAR`

Examples

```
#Example 1: Find an ARp subset model for lynx data using BIC
z<-log(lynx)
out<-SelectModel(z, SubsetModel="p", Criterion="BIC", Best=5)
plot(out)
#
#Example 2: Find an ARz subset model for lynx data using BIC
out<-SelectModel(z, SubsetModel="z", Criterion="BIC", Best=5)
plot(out)
#
#Example 3: Select an AR(p) model
out<-SelectModel(z, Criterion="BIC", Best=5)
out
plot(out)
#
#Example 4: Fit subset models to lynx series
z<-log(lynx)
#requires library leaps. Should be automatically when FitAR package is loaded.
pvec <- SelectModel(z, lag.max=11, SubsetModel="p", Criterion="AIC", Best=1)
ans1 <- FitARLS(z, pvec)
pvec <- SelectModel(z, lag.max=11, SubsetModel="z", Criterion="AIC", Best=1)
ans2<-FitAR(z, pvec)
summary(ans1)
summary(ans2)
```

SeriesA

Series A, Chemical Process Concentration Readings

Description

Chemical process concentration readings for every 2 hours.

Usage

```
data(SeriesA)
```

Format

ts object with attribute "title"

Details

Box and Jenkins (1970) fit an ARMA(1,1) and ARIMA(0,1,1) to this series. Cleveland() suggested a subset AR(1,2,7). McLeod and Zhang (2006) fit a subset ARz(1,2,6,7) parameterized with the partial autocorrelations.

Source

Box and Jenkins (1970). Time Series Analysis: Forecasting and Control.

References

- Cleveland, W.S. (1971) The inverse autocorrelations of a time series and their applications. *Tech-nometrics* 14, 277-298.
- McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregres-sion. *Journal of Time Series Analysis*, 27, 599-612.

Examples

```
data(SeriesA)
#fit subset models
FitARLS(SeriesA, c(1,2,7))
FitAR(SeriesA, c(1,2,6,7))
```

SiddiquiMatrix

Covariance Matrix of MLE Parameters in an AR(p)

Description

A direct method of computing the inverse of the covariance matrix of p successive observations in an AR(p) with unit innovation variance given by Siddiqui (1958) is implemented. This matrix, divided by n = length of series, is the covariance matrix for the MLE estimates in a regular AR(p).

Usage

```
SiddiquiMatrix(phi)
```

Arguments

phi	coefficients in a regular AR(p)
-----	---------------------------------

Value

Matrix, covariance matrix of MLE estimates

Note

No check on whether the parameters are in the stationary region is done. It has been shown a necessary and sufficient condition for the parameters to be in the stationary region is that this matrix should be positive-definite (Pagano, 1973). But computationally it is probably better to test for stationarity by using [ARToPacf](#) to transform to the PACF and then check that the absolute value of all partial autocorrelations are less than 1.

Author(s)

A.I. McLeod

References

- Siddiqui, M.M. (1958) On the inversion of the sample covariance matrix in a stationary autoregres-sive process. *Annals of Mathematical Statistics* 29, 585-588.
- Pagano, M. (1973), When is an autoregressive scheme stationary? *Communications in Statistics A* 1, 533-544.

See Also

[FitAR](#), [FitARLS](#)

Examples

```
#compute the inverse directly and by Siddiqui's method and compare:
phi<-PacfToAR(rep(0.8,5))
A<-SiddiquiMatrix(phi)
B<-solve(toeplitz(TacvfAR(phi, lag.max=length(phi)-1)))
max (abs (A-B) )
```

SimulateGaussianAR *Autoregression Simulation*

Description

Simulate a mean-zero stationary Gaussian AR(p) time series.

Usage

```
SimulateGaussianAR(phi, n = 100, InnovationVariance = 1)
```

Arguments

phi	vector containing AR coefficients
n	length of time series
InnovationVariance	innovation variance

Details

The p initial values are simulated using the appropriate multivariate distribution as was suggested in McLeod (1975). The R function `rnorm()` is used.

Value

A vector of length n , the simulated series

Note

If the process is non-stationary, then random initial values are used determined by the first p innovations.

Author(s)

A.I. McLeod

References

McLeod, A.I. (1975), Derivation of the theoretical autocorrelation function of autoregressive moving-average time series, *Applied Statistics* **24**, 255–256.

Percival, D.B. and Walden, A.T. (1993), *Spectral Analysis for Physical Applications*.

See Also

[Boot.FitAR](#)

Examples

```
#Percival and Walden (1993, p.46) illustrated a time series with a
#very peaked spectrum with the AR(4) with coefficients
#c(2.7607,-3.8106,2.6535,-0.9238) with NID(0,1) innovations.
#
z<-SimulateGaussianAR(c(2.7607,-3.8106,2.6535,-0.9238),1000)
library(lattice)
TimeSeriesPlot(z)
```

TacvfAR

*Theoretical Autocovariance Function of AR***Description**

The theoretical autocovariance function of an AR(p) with unit variance is computed. This algorithm has many applications. In this package it is used for the computation of the information matrix, in simulating p initial starting values for AR simulations and in the computation of the exact mle for the mean.

Usage

```
TacfAR(phi, lag.max = 20)
```

Arguments

phi	vector of AR coefficients
lag.max	computes autocovariances lags 0,1,...,maxlag

Details

The algorithm given by McLeod (1975) is used.

The built-in R function ARMAacf could also be used but it is quite complicated and apart from the source code, the precise algorithm used is not described. The only reference given for ARMAacf is the Brockwell and Davis (1991) but this text does not give any detailed exact algorithm for the general case.

Another advantage of TacfAR over ARMAacf is that it will be easier for to translate and implement this algorithm in other computing environments such as MatLab etc. since the code is entirely written in R.

Value

Vector of length lag.max+1 containing the autocovariances at lags 0,...,lag.max is returned.

Author(s)

A.I. McLeod

References

McLeod, A.I. (1975), Derivation of the theoretical autocorrelation function of autoregressive moving-average time series. *Applied Statistics*, 24, 255-256.

See Also

[ARMAacf](#), [InformationMatrixAR](#), [GetARMeanMLE](#), [SimulateGaussianAR](#)

Examples

```
#calculate and plot the autocorrelations from an AR(2) model
# with parameter vector c(1.8,-0.9).
g<-TacvfAR(c(1.8,-0.9),20)
AcfPlot(g/g[1], LagZeroQ=FALSE)
```

Description

The theoretical autocovariance function of a MA(q) with unit variance is computed.

Usage

```
TacvfMA(theta, lag.max = 20)
```

Arguments

theta	q parameters in MA(q)
lag.max	number of lags required.

Details

The first q+1 values are determined using a matrix multiplication - avoiding a loop. The remaining values set to zero.

Value

Vector of length q+1 containing the autocovariances at lags 0,1,...,lag.max

Note

See Details in [TacvfAR](#) for why we prefer to use this algorithm instead of [ARMAacf](#)

Author(s)

A.I.McLeod

References

McLeod, A.I. and Zhang, Y. (2006), Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[ARMAacf](#), [TacvfAR](#)

Examples

```
TacvfMA(c(1.8,, -0.9), 10)
```

[TimeSeriesPlot](#)

Multi-Panel or Single-Panel Time Series Plot with Aspect-Ratio Control

Description

Cleveland pointed out that the aspect-ratio is important in graphically showing the rate-of-change or shape information. For many time series, it is preferably to set this ratio to 0.25 than the default. In general, Cleveland shows that the best choice of aspect-ratio is often obtained by if the average apparent absolute slope in the graph is about 45 deg. But for many stationary time series, this would result in an aspect-ratio which would be too small. As a comprise we have chosen a default of 0.25 but the user can select other choices.

Usage

```
TimeSeriesPlot(z, SubLength = Inf, aspect = 0.25, type="l", ylab=NULL, main=NULL)
```

Arguments

<code>z</code>	ts object or vector, time series data
<code>SubLength</code>	maximum number of data points per panel. Default SubLength=Inf and regular graphics. For trellis graphics, set SubLength to a finite value.
<code>aspect</code>	optional setting for the aspect-ratio
<code>type</code>	plot type, default type="l" join points with lines
<code>ylab</code>	optional label for vertical axis
<code>main</code>	optional title
<code>...</code>	optional arguments passed to <code>xyplot</code>

Details

If `z` has attribute "title" containing a character string, this is used on the plot. Time series input using the function [Readts](#) always have this attribute set.

Value

If `SubLength` is finite, the lattice package is used and a graphic object of class `trellis` is produced. Otherwise, the standard R graphics system is used and the plot is produced as a side-effect and there is no output.

Note

Requires `lattice` library

Author(s)

A.I. McLeod

References

W.S. Cleveland (1993), *Visualizing Data*.

See Also

[plot.ts](#), [Readts](#)

Examples

```
#from built-in datasets
TimeSeriesPlot(AirPassengers)
title(main="Monthly number of trans-Atlantic airline passengers")
#
#compare plots for lynx series
plot(lynx)
win.graph()
TimeSeriesPlot(lynx, type="o", pch=16, ylab="# pelts", main="Lynx Trappings")
#
#lattice style plot
data(Ninemile)
TimeSeriesPlot(Ninemile, SubLength=200)
```

USTobacco

U.S. Tobacco Production, 1871-1984

Description

Annual U.S. tobacco production, 1871-1984, in millions of pounds.

Usage

`data(USTobacco)`

Format

The format is: Time-Series [1:114] from 1871 to 1984: 327 385 382 217 609 466 621 455 472 469
... - attr(*, "title")= chr "Tobacco production,US, 1871-1984"

Details

Wei (2006, p.120, Example 6.6) fits an ARIMA(0,1,1) to the logarithms. But a more accurate Box-Cox analysis indicates a square-root transformation should be used. A more complex ARIMA-GARCH model is also suggested by Wei (2006).

Source

Wei, W.W.S. (2006, Series W6, p.570), *Time Series Analysis: Univariate and Multivariate Methods*. 2nd Ed., New York: Addison-Wesley.

Examples

```
#From a plot of the series, we see that the variance is increasing with level.
#From the acf of the first differences an ARIMA(0,1,1) is suggested.
data(USTobacco)
# layout(matrix(c(1,2,1,2),ncol=2))
plot(USTobacco)
lines(lowess(time(USTobacco), USTobacco), lwd=2, col="blue")
acf(diff(USTobacco, differences=1))
```

VarianceRacfAR

Covariance Matrix Residual Autocorrelations for AR

Description

Computes the variance-covariance matrix for the residual autocorrelations in an AR(p).

Usage

```
VarianceRacfAR(phi, MaxLag, n)
```

Arguments

phi	vector of AR coefficients
MaxLag	covariance matrix for residual autocorrelations at lags 1,...,m, where m=MaxLag is computes
n	length of time series

Details

The covariance matrix for the residual autocorrelations is derived in McLeod (1978, eqn. 15) for the general ARMA case. With this function one can obtain the standard deviations of the residual autocorrelations which can be used for diagnostic checking with [RacfPlot](#).

Value

The m-by-m covariance matrix of residual autocorrelations at lags 1,...,m, where m=MaxLag.

Note

The derivation assumes normality of the innovations, mle estimation of the parameters and a known mean-zero time series. It is easily seen that the same result still holds for IID innovations with mean zero and finite variance, any first-order efficient estimates of the parameters including the AR coefficients and mean.

Author(s)

A.I. McLeod

References

McLeod, A.I. (1978), On the distribution and applications of residual autocorrelations in Box-Jenkins modelling, *Journal of the Royal Statistical Society B*, **40**, 296–302

See Also

[VarianceRacfARp](#), [VarianceRacfARz](#), [RacfPlot](#)

Examples

```
VarianceRacfAR(0.5, 5, 100)
```

`VarianceRacfARp`

Covariance Matrix Residual Autocorrelations for ARp

Description

The ARp subset model is defined by taking a subset of the parameters in the regular AR(p) model. With this function one can obtain the standard deviations of the residual autocorrelations which can be used for diagnostic checking with [RacfPlot](#).

Usage

```
VarianceRacfARp(phi, lags, MaxLag, n)
```

Arguments

phi	vector of AR coefficients
lags	lags in subset AR
MaxLag	covariance matrix for residual autocorrelations at lags 1,...,m, where m=MaxLag is computes
n	length of time series

Details

The covariance matrix for the residual autocorrelations is derived in McLeod (1978, eqn. 15) for the general ARMA case. McLeod (1978, eqn. 35) specializes this result to the subset case.

Value

The m-by-m covariance matrix of residual autocorrelations at lags 1,...,m, where m=MaxLag.

Author(s)

A.I. McLeod

References

McLeod, A.I. (1978), On the distribution and applications of residual autocorrelations in Box-Jenkins modelling, *Journal of the Royal Statistical Society B*, **40**, 296-302.

See Also

[VarianceRacfAR](#), [VarianceRacfARz](#), [RacfPlot](#)

Examples

```
#the standard deviations of the first 5 residual autocorrelations
#to a subset AR(1,2,6) model fitted to Series A is
v<-VarianceRacfARp(c(0.36,0.23,0.23),c(1,2,6), 5, 197)
sqrt(diag(v))
```

VarianceRacfARz

Covariance Matrix Residual Autocorrelations for ARz

Description

The ARz subset model is defined by taking a subset of the partial autocorrelations (zeta parameters) in the AR(p) model. With this function one can obtain the standard deviations of the residual autocorrelations which can be used for diagnostic checking with [RacfPlot](#).

Usage

```
VarianceRacfARz(zeta, lags, MaxLag, n)
```

Arguments

zeta	zeta parameters (partial autocorrelations)
lags	lags in model
MaxLag	covariance matrix for residual autocorrelations at lags 1,...,m, where m=MaxLag is computes
n	length of time series

Details

The covariance matrix of the residual autocorrelations in the subset ARz case is derived in McLeod and Zhang (2006, eqn. 16)

Value

The m-by-m covariance matrix of residual autocorrelations at lags 1,...,m, where m=MaxLag.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[VarianceRacfAR](#), [VarianceRacfARz](#), [RacfPlot](#)

Examples

```
#the standard deviations of the first 5 residual autocorrelations
#to a subset AR(1,2,6) model fitted to Series A is
v<-VarianceRacfARp(c(0.36,0.23,0.23),c(1,2,6), 5, 197)
sqrt(diag(v))
```

Willamette

Willamette Riverflow Time Series

Description

Monthly flows of the Willamette River, Salem, Oregon, Oct. 1950 - Aug. 1983. Percival and Walden (1993, Ch. 10.15) fit high-order AR models to estimate the spectral density function.

Usage

```
data(Willamette)
```

Format

The format is: Time-Series [1:395] from 1951 to 1984: 8.95 9.49 10.19 10.96 11.08 ... - attr(*, "title")= chr "Willamette river, Monthly, Salem, Oregon, Oct. 1950 - Aug. 1983"

Source

<http://faculty.washington.edu/dbp/sapabook.html>

References

Percival, D.B. and Walden, A.T. (1993), *Spectral Analysis for Physical Applications*. Cambridge University Press.

Examples

```
#Percival and Walden (1993) fit an AR(27).
#Compare spectral densities with subset AR's.
data(Willamette)
pmax<-27
sdfplot(FitAR(log(Willamette), pmax))
win.graph()
p<-SelectModel(log(Willamette), SubsetModel="z", lag.max=pmax, Best=1)
sdfplot(FitAR(log(Willamette), p))
win.graph()
p<-SelectModel(log(Willamette), SubsetModel="p", lag.max=pmax, Best=1)
sdfplot(FitARLS(log(Willamette), p))
```

bxcx

*Box-Cox Transformation and its Inverse***Description**

Box-Cox or power transformation or its inverse. For $\lambda \neq 0$, the Box-Cox transformation of x is $(x - 1)^\lambda / \lambda$ whereas the regular power transformation is simply x^λ . When $\lambda = 0$, it is log in both cases. The inverse of the Box-Cox and the power transform can also be obtained.

Usage

```
bxcx(x, lambda, InverseQ = FALSE, type = "BoxCox")
```

Arguments

<code>x</code>	a vector or time series
<code>lambda</code>	power transformation parameter
<code>InverseQ</code>	if TRUE, the inverse transformation is done
<code>type</code>	either "BoxCox" or "power"

Value

a vector or time series of the transformed data

Author(s)

A.I. McLeod

References

Box, G. E. P. and Cox, D. R. (1964) An analysis of transformations. Journal of Royal Statistical Society, Series B, vol. 26, pp. 211-246.

See Also

[BoxCox](#)

Examples

```
#lambda=0.5
z<-AirPassengers; lambda<-0.5
y<-bxcx(z, lambda)
z2<-bxcx(y, lambda, InverseQ=TRUE)
sum(abs(z2-z))
#
z<-AirPassengers; lambda<-0.0
y<-bxcx(z, lambda)
z2<-bxcx(y, lambda, InverseQ=TRUE)
sum(abs(z2-z))
```

coef.FitAR

*Display Estimated Parameters from Output of FitAR***Description**

Method function to display fitted parameters, their standard errors and Z-ratio for AR models fit with FitAR and FitARLS.

Usage

```
## S3 method for class 'FitAR':
coef(object, ...)
```

Arguments

object	obj the output from FitAR or FitARLS
...	optional parameters

Value

A matrix is returned. The columns of the matrix are labeled MLE, sd and Z-ratio. The rows labels indicate the AR coefficients which were estimated followed by mu, the estimate of mean.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. Journal of Time Series Analysis, 27, 599-612.

Examples

```
# Fit subset AR to SeriesA
data(SeriesA)
outA<-FitAR(SeriesA, c(1,2,7))
coef(outA)
#
outALS<-FitARLS(SeriesA, c(1,2,7))
coef(outALS)
```

`fitted.FitAR` *Fitted Values from "FitAR" Object*

Description

Method function, extracts fitted values from FitAR object.

Usage

```
## S3 method for class 'FitAR':
fitted(object, ...)
```

Arguments

<code>object</code>	object of class "FitAR"
<code>...</code>	optional arguments

Value

vector of fitted values

Author(s)

A.I. McLeod

See Also

[FitAR](#), [FitARLS](#),

Examples

```
data(SeriesA)
out<-FitAR(SeriesA, c(1,2,6,7))
fitted(out)
```

`plot.FitAR` *Plot Method for "FitAR" Object*

Description

Diagnostic plots: portmanteau p-values; residual autocorrelation plot; normal probability plot and Jarque-Bera test; spectral density function

Usage

```
plot.FitAR(x, clearGraphics=TRUE, verbose=TRUE, ...)
```

Arguments

```

x          object of class "FitAR"
clearGraphics    close all graphics windows
terse      if TRUE, only one graph is produced, otherwise many diagnostic plots.
...        optional arguments

```

Value

No value is returned. Plots are produced as side-effect.

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[summary.FitAR](#), [FitAR](#), [FitARLS](#) [JarqueBeraTest](#) [RacfPlot](#) [LBQPlot](#)

Examples

```

data(SeriesA)
obj<-FitAR(SeriesA, c(1,2,6,7))
plot(obj)

```

plot.Selectmodel *Subset AR Graph for "Selectmodel" Object*

Description

A graphical depiction is given of the output from `SelectModel`.

Usage

```
plot.Selectmodel(x, ...)
```

Arguments

```

x          out from SelectModel
...        optional arguments

```

Details

The relative plausibility of Model A vs the best Model B, is defined as $R = e^{(AIC_B - AIC_A)/2}$. Values of R less than 1 R is defined similarly if the BIC/UBIC criterion is used.

Value

No value. Plot produced as side-effect.

Author(s)

A.I. McLeod

See Also

[SelectModel](#)

Examples

```
data(Willamette)
out<-SelectModel(log(Willamette),lag.max=150,SubsetModel="n",Best=5,Criterion="AIC")
plot(out)
```

print.FitAR *Print Method for "FitAR" Object*

Description

A terse summary is given

Usage

```
print.FitAR(x, ...)
```

Arguments

x	object of class "FitAR"
...	optional arguments

Value

A terse summary is displayed

Author(s)

A.I. McLeod

References

McLeod, A.I. and Zhang, Y. (2006). Partial autocorrelation parameterization for subset autoregression. *Journal of Time Series Analysis*, 27, 599-612.

See Also

[summary.FitAR](#), [FitARLS](#)

Examples

```
data(SeriesA)
FitAR(SeriesA, c(1,2,6,7))
```

residuals.FitAR *Extract Residual from "FitAR" Object*

Description

Method function.

Usage

```
## S3 method for class 'FitAR':  
residuals(object, ...)
```

Arguments

object	object of class "FitAR"
...	optional arguments

Value

Vector of residuals

Author(s)

A.I. McLeod

See Also

[FitAR](#), [FitARLS](#),

Examples

```
data(SeriesA)  
out<-FitAR(SeriesA, c(1,2,6,7))  
resid(out)
```

sdfplot.Arima *Spectral Density of Fitted ARIMA Model*

Description

Method for class "Arima" for sdfplot.

Usage

```
sdfplot.Arima(obj, ...)
```

Arguments

obj	object class "Arima"
...	optional arguments

Value

None. Plot is produced using `plot`.

Author(s)

A.I. McLeod

See Also

`ARSdf`, `sdfplot`, `sdfplot.FitAR`, `sdfplot.ts`

Examples

```
data(SeriesA)
sdfplot(SeriesA,c(1,0,1))
```

`sdfplot.FitAR` *Autoregressive Spectral Density Estimation for "FitAR"*

Description

Methods function for `sdfplot`. Autoregressive spectral density function estimation using the result output from `FitAR`.

Usage

```
## S3 method for class 'FitAR':
sdfplot(obj, ...)
```

Arguments

<code>obj</code>	object, class "FitAR"
<code>...</code>	optional arguments

Value

Plot produced as side-effect. No output.

Author(s)

A.I. McLeod

See Also

`sdfplot`, `FitAR`, `FitARLS`

Examples

```
#Use AIC to select best subset model to fit to lynx data and
#plot spectral density function
data(SeriesA)
pvec<-SelectModel(SeriesA, SubsetModel="p", lag.max=10, Best=1)
ans<-FitAR(SeriesA, pvec)
sdfplot(ans)
#
#plot sdf and put your own title
z<-c(SeriesA)
pvec<-SelectModel(z, SubsetModel="p", lag.max=10, Best=1)
ans<-FitAR(z, pvec)
sdfplot(ans)
title(main="Example SDF")
```

sdfplot

Autoregressive Spectral Density Estimation

Description

Generic function. Methods are available for "FitAR", "ar", "Arima", "ts" and "numeric".

Usage

```
sdfplot(obj, ...)
```

Arguments

obj	input object
...	optional arguments

Value

Plot produced as side-effect. No output.

Author(s)

A.I. McLeod

See Also

[sdfplot](#), [FitAR](#), [FitARLS](#)

Examples

```
#Use AIC to select best subset model to fit to lynx data and
#plot spectral density function
data(SeriesA)
pvec<-SelectModel(SeriesA, SubsetModel="p", lag.max=10, Best=1)
ans<-FitAR(SeriesA, pvec)
sdfplot(ans)
#
# fit ARMA and plot sdf
```

```
ans<-arima(SeriesA, c(1,0,1))
sdfplot(ans)
```

sdfplot.ar*Autoregressive Spectral Density Estimation for "ar"***Description**

Method for class "ar" for sdfplot.

Usage

```
## S3 method for class 'ar':
sdfplot(obj, ...)
```

Arguments

obj	class "ar" object, output from ar
...	optional arguments

Value

None. Plot is produced using plot

Author(s)

A.I. McLeod

See Also

[ARSdf](#), [sdfplot](#), [sdfplot.FitAR](#), [sdfplot.ts](#)

Examples

```
#Fit AR(p) using AIC model selection and Burg estimates. Plot spectral density
#estimate
ans<-ar(lynx, lag.max=20)
sdfplot(ans)
```

`sdfplot.numeric` *Autoregressive Spectral Density Estimation for "numeric"*

Description

Method function for vectors, class "numeric"

Usage

```
## S3 method for class 'numeric':
sdfplot(obj, ...)
```

Arguments

<code>obj</code>	object, class "numeric", a vector
<code>...</code>	optional arguments

Value

Plot produced as side-effect. No output.

Author(s)

A.I. McLeod

See Also

[sdfplot](#)

Examples

```
sdfplot(lynx)
```

`sdfplot.ts` *Autoregressive Spectral Density Estimation for "ts" Object*

Description

Methods function for "ts".

Usage

```
## S3 method for class 'ts':
sdfplot(obj, ...)
```

Arguments

<code>obj</code>	object, class "ts"
<code>...</code>	optional arguments

Value

Plot produced as side-effect. No output.

Author(s)

A.I. McLeod

See Also

[sdfplot](#)

Examples

```
data(SeriesA)
sdfplot(SeriesA)
```

summary.FitAR *Summary Method for "FitAR" Object*

Description

summary for "FitAR" object

Usage

```
## S3 method for class 'FitAR':
summary(object, ...)
```

Arguments

object	"FitAR" object
...	optional arguments

Value

A printed summary is given

Author(s)

A.I. McLeod

See Also

[print.FitAR](#), [FitAR](#), [FitARLS](#),

Examples

```
data(SeriesA)
out<-FitAR(SeriesA, c(1,2,6,7))
summary(out)
```

Index

*Topic **array**
FromSymmetricStorageUpper, 23

*Topic **datasets**
Ninemile, 40
SeriesA, 49
USTobacco, 55
Willamette, 59

*Topic **htest**
JarqueBeraTest, 35

*Topic **ts**
AcfPlot, 5
AR1Est, 1
ARSdf, 2
ARToMA, 3
ARToPacf, 4
BackcastResidualsAR, 6
Boot, 8
Boot.FitAR, 7
Boot.ts, 9
BoxCox, 13
BoxCox.Arima, 10
BoxCox.FitAR, 11
BoxCox.numeric, 14
BoxCox.ts, 15
bxcx, 60
ChampernowneD, 16
coef.FitAR, 61
DetAR, 17
FastLoglikelihoodAR, 18
FitAR, 19
FitARLS, 21
fitted.FitAR, 62
FromSymmetricStorageUpper, 23
Get1G, 23
GetARMeanMLE, 24
GetB, 25
GetFitAR, 26
GetFitARLS, 27
GetKappa, 28
GetLeapsAR, 28
InformationMatrixAR, 30
InformationMatrixARp, 31
InformationMatrixARz, 32

InvertibleQ, 33
Jacobian, 34
JacobianK, 35
LBQPlot, 36
LjungBoxTest, 37
LoglikelihoodAR, 39
PacfDL, 41
PacfPlot, 42
PacfToAR, 43
plot.FitAR, 62
plot.Selectmodel, 63
PlotARSdf, 44
print.FitAR, 64
RacfPlot, 45
Readts, 46
residuals.FitAR, 65
sdfplot, 67
sdfplot.ar, 68
sdfplot.Arima, 65
sdfplot.FitAR, 66
sdfplot.numeric, 69
sdfplot.ts, 69
SelectModel, 47
SiddiquiMatrix, 50
SimulateGaussianAR, 51
summary.FitAR, 70
TacfAR, 52
TacfMA, 53
TimeSeriesPlot, 54
VarianceRacfAR, 56
VarianceRacfARp, 57
VarianceRacfARz, 58

acf, 5, 41, 42
AcfPlot, 5
ar, 22, 41, 42
ar.burg, 43
AR1Est, 1
arima, 11
ARMAacf, 53, 54
ARSdf, 2, 44, 66, 68
ARToMA, 3
ARToPacf, 4, 33, 50

BackcastResidualsAR, 6, 22
 Boot, 7, 8
 Boot.FitAR, 7, 8, 9, 52
 Boot.ts, 9
 Box.test, 38
 BoxCox, 11, 12, 13, 60
 BoxCox.Arima, 10, 12–14, 16
 BoxCox.FitAR, 11, 11, 13, 14, 16
 BoxCox.numeric, 13, 14, 16
 BoxCox.ts, 13, 14, 15
 bxcx, 60

 ChampernowneD, 16, 18
 coef.FitAR, 61

 DetAR, 17

 FastLoglikelihoodAR, 17, 18, 18, 39
 FitAR, 6, 17, 19, 22, 26, 28, 30, 32, 37, 45,
 46, 48, 51, 62, 63, 65–67, 70
 FitARLS, 20, 21, 27, 28, 31, 37, 45, 46, 51,
 62–67, 70
 fitted.FitAR, 62
 FromSymmetricStorageUpper, 23

 Get1G, 23
 GetARMeanMLE, 24, 24, 53
 GetB, 25
 GetFitAR, 2, 17, 26, 28
 GetFitARLS, 27, 29
 GetKappa, 28
 GetLeapsAR, 28

 InformationMatrixAR, 30, 31, 32, 53
 InformationMatrixARp, 30, 31, 32
 InformationMatrixARz, 30, 31, 32, 34
 InvertibleQ, 3, 4, 6, 33, 44

 Jacobian, 34, 35
 JacobianK, 35
 JarqueBeraTest, 35, 63

 LBQPplot, 36, 63
 leaps, 29
 LjungBoxTest, 37
 LoglikelihoodAR, 18, 22, 28, 39
 lsfit, 27

 mean, 25

 Ninemile, 40

 pacf, 43
 PacfDL, 41, 41